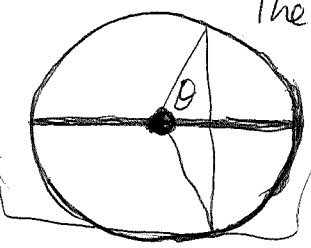


α'' What do you want to know about T?

$T: V_+ \rightarrow V_-$. The obvious symmetry group acting on the $\{W \in \binom{V_+}{V_-}\}$ is $\begin{pmatrix} U(V_+) & 0 \\ 0 & U(V_-) \end{pmatrix}$. W same

as a $g \in \mathfrak{g} \ni \varepsilon g \varepsilon^{-1} = g^{-1}$. There's a spectrum, the main part being $\cos \theta \in (-1, 1)$ and

How are you going



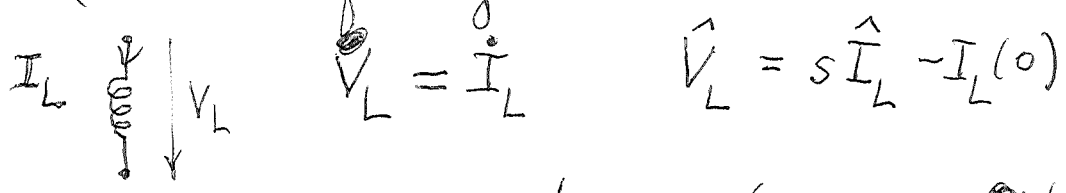
4 degenerate cases. $F = \pm 1, \varepsilon = \pm 1$.

to replace, improve upon the

resolvent $\begin{pmatrix} s & T^* \\ -T & s \end{pmatrix}^{-1} = \begin{pmatrix} s & - \begin{pmatrix} 0 & T^* \\ T & 0 \end{pmatrix} \end{pmatrix}^{-1} = \frac{1}{s-X}, X = \begin{pmatrix} 0 & T^* \\ T & 0 \end{pmatrix}$

~~Problem:~~ Problem: ~~What~~ Given $W \in \binom{V_+}{V_-}$ of F, ε on Euclidean space V , what is the mathematical object you need to describe the associated abstract LC ~~network~~ network. Look at a concrete LC network, it has a state space and time evolutions. ~~What is~~ state space is

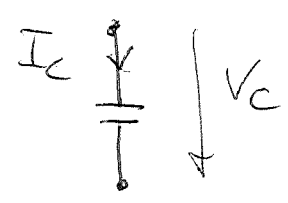
need review of degenerate cases.



$$\begin{matrix} \bar{C}^0 & \xrightarrow{\sim} & C_{L,0}^1 \\ & & \uparrow s \\ \bar{C}_0 & \xleftarrow{\sim} & C_{L,0} \end{matrix} \quad \begin{pmatrix} V_L \\ I_L \end{pmatrix} \quad \begin{pmatrix} s \\ 1 \end{pmatrix} I_L = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

intersect $\bar{C}^0 = C_L^1$ with $\begin{pmatrix} s \\ 1 \end{pmatrix} I_L$ can happen

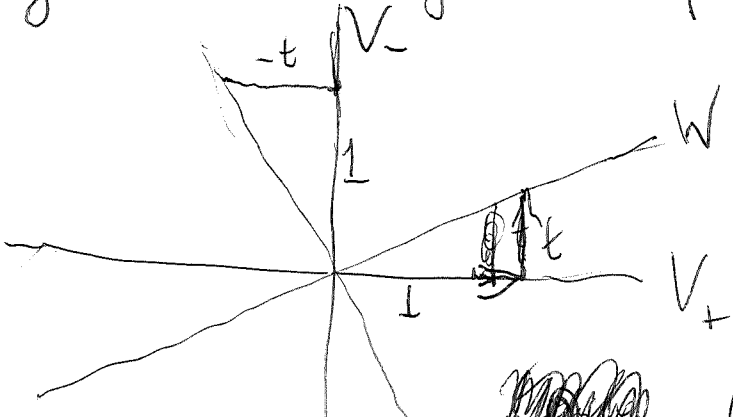
when $s = \infty$



$$\begin{matrix} \bar{C}^0 = C_C^1 \\ \downarrow s \\ \bar{C}_0 = C_{C,0} \end{matrix} \quad \text{intersect} \quad \bar{C}^0 = C_C^1 \quad \begin{pmatrix} 1 \\ s \end{pmatrix} V_C \quad \begin{pmatrix} * \\ 0 \end{pmatrix} \quad s = 0$$

"B" You need the direct sum of simple situations.
 Let's ~~look at~~ look at phases in the s.h.o. cases.

$W \leftarrow \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \quad \underline{1} = \alpha^* \alpha = \begin{pmatrix} \alpha_+^* & \alpha_-^* \end{pmatrix} \begin{pmatrix} \alpha_+ \\ \alpha_- \end{pmatrix} = \alpha_+^* \alpha_+ + \alpha_-^* \alpha_- = h_+ + h_-$
~~orthogonal~~ orthogonal structure $(x, x) = x^2$. $\dim(W) = 1$. You have
 $g = F_2$ an orthogonal transf.



$$F \begin{pmatrix} 1 & -t \\ t & 1 \end{pmatrix} = \begin{pmatrix} 1 & -t \\ t & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$F \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

~~Q:~~ Q: Is there a phase ambiguity in this 2d case? Given W can view it as the graph of multipl by $t: V_+ \rightarrow V_-$. Then you get

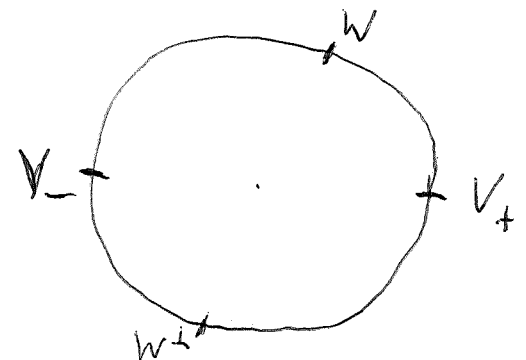
$$F \begin{pmatrix} 1 & -t \\ t & 1 \end{pmatrix} \frac{1}{\sqrt{1+t^2}} = \begin{pmatrix} 1 & -t \\ t & 1 \end{pmatrix} \frac{1}{\sqrt{1+t^2}} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$F \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix}$$

$$F = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \cos 2\alpha & \sin 2\alpha \\ -\sin 2\alpha & \cos 2\alpha \end{pmatrix} = \begin{pmatrix} \cos 2\alpha & \sin 2\alpha \\ \sin 2\alpha & \cos 2\alpha \end{pmatrix} \varepsilon$$

so $g = \begin{pmatrix} \cos 2\alpha & -\sin 2\alpha \\ \sin 2\alpha & \cos 2\alpha \end{pmatrix} \quad g^{1/2} = \pm \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$



back to the phase business. first recall the details, then write it down. Begin with the complex case: a unitary repn of F_2 on V , s.t. $\frac{g+g^{-1}}{2} = \text{scalar operator } \cos\theta$ where $0 < \theta < \pi$. Then $V = V_\theta \oplus V_{-\theta}$ where $g = e^{\pm i\theta}$ on $V_{\pm\theta}$. $\varepsilon g \varepsilon^{-1} = g^{-1} \Rightarrow \varepsilon: V_\theta \xleftrightarrow{\sim} V_{-\theta}$

~~map~~ $\varepsilon: V_\theta \xrightarrow{\sim} V_{-\theta}$ is a canon. isom. with inverse ε .

At this point you want to identify the repn. V, F_2, ε with ~~the~~ a Hilbert $W \otimes$ irred rep. V_λ .

~~what's the~~ The clearest way to proceed is to choose an orthonormal basis v_i for V_θ , then $v_i, \varepsilon v_i$ give an orth basis for V . Say $n=1$, so one has a unit vector $v \in V_\theta$ and one $\varepsilon v \in V_{-\theta}$. Relative to this basis

$$\varepsilon = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad g = \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}^{\frac{1}{2}} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}^{\frac{1}{2}} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

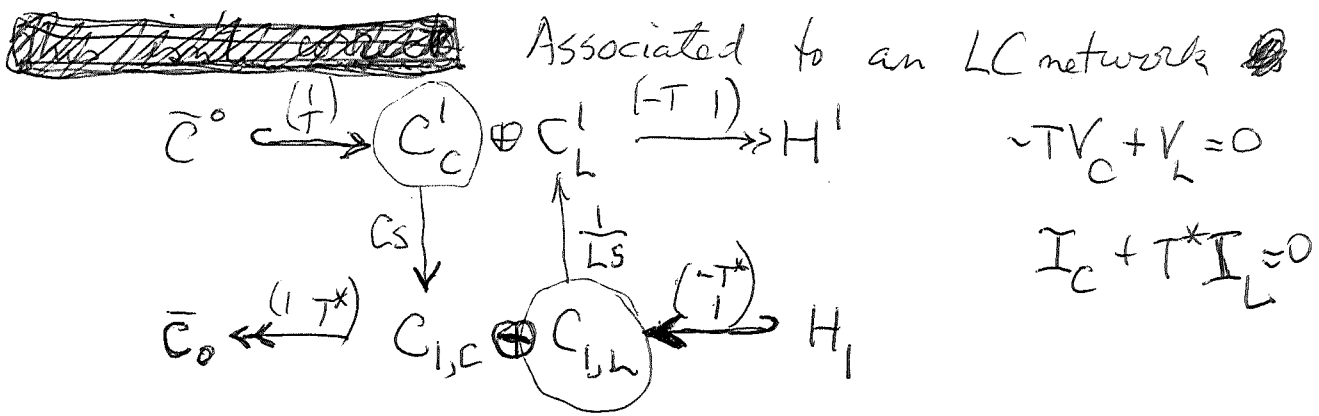
$$\begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} \xi & 0 \\ 0 & \bar{\xi} \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}^{\frac{1}{2}} = \begin{pmatrix} \xi & \bar{\xi} \\ -\xi & \bar{\xi} \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}^{\frac{1}{2}} = \begin{pmatrix} \cos\theta & -\sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} \xi & 0 \\ 0 & \bar{\xi} \end{pmatrix} \begin{pmatrix} 1 & -i \\ 1 & i \end{pmatrix}^{\frac{1}{2}} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$$

maybe best is to exhibit I_λ "the" irred. rep. and then ~~construct~~ find $\text{Hom}_{F_2}(I_\lambda, V)$

S'' Next - how does T arise? ~~Do~~ You consider $W \subset \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$, better, a ^{unitary} n reps of F, ε on V such that $\frac{g+g^{-1}}{2}$ has spectrum $\in (-1, 1)$. In fact you want " " " $(-1, 1]$ for $W = \begin{pmatrix} 1 \\ T \end{pmatrix} V_+$.
 Then $F \begin{pmatrix} 1 & -T^* \\ T & 1 \end{pmatrix} = \begin{pmatrix} 1 & -T^* \\ T & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

~~What is the aim?~~ Aim? You want a clean clear picture of an abstract LC network. Can you give a definition? You can define an LC network (assumed connected) to be a ^{connected} graph whose edges are labelled with either an $L > 0$ or a $C > 0$.



are short exact sequences of cochains and chains, which are naturally in duality. How to organize this? First you ~~use~~ use $s=1$ to make a pos. def quad form on C^1_C , or to ^{naturally} identify $C^1_C = C_{1,C}$.

Sim for L $\hat{V}_C = I_C \implies \hat{I}_C = \hat{V}_C = -V_C(0) + s \hat{V}_C$
 $\hat{I}_L = V_L \implies \hat{V}_L = \hat{I}_L = -I_L(0) + s \hat{I}_L$
 $s \hat{V}_C + T^* \hat{I}_L = V_C(0)$
 $-T \hat{V}_C + s \hat{I}_L = I_L(0)$

Can you somehow make this meaningful? concrete?
 Important $s \in \mathbb{C} \cup \infty$ (it characterizes)
 Idea: normal form (T replaced by \hat{V})
 Ultimate picture should involve an eigenspace decomp of $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$

ε'' The ~~ultimate~~ ultimate picture should involve an eigenspace decomposition of the ^{orthogonal} representation of F, ε on V , i.e. an ^{orthogonal} decomposition of the given repr of F, ε into irreducible representations. ~~the problem is~~

Essentially this amounts to the eigenspace decamp of the ~~symmetric~~ symmetric operator $\frac{1}{2}(g+g^{-1})$. What does this look like? The ^{possible} spectrum is $[-1, 1]$.

You need to relate the eigenvalue λ for $\frac{1}{2}(g+g^{-1})$ the ~~partitioning~~ ^{partitioning of 1} operators: $1 = h_+ + h_- = \alpha_+^* \alpha_+ + \alpha_-^* \alpha_-$ and the frequency variable ω such that $h_+ = \frac{1}{1+\omega^2}$

$$h_- = \frac{\omega^2}{1+\omega^2} \quad \mathbb{R} \xrightarrow{\begin{pmatrix} 1 \\ \omega \end{pmatrix} (1+\omega^2)^{-1/2}} \begin{pmatrix} \mathbb{R} \\ \mathbb{R} \end{pmatrix} \xrightarrow{\begin{pmatrix} \omega & +1 \\ (1+\omega^2)^{1/2} \end{pmatrix}} \mathbb{R}$$

$$\alpha_+ = \frac{1}{\sqrt{1+\omega^2}}, \quad \alpha_- = \frac{\omega}{\sqrt{1+\omega^2}}$$

$$\therefore h_+ = \frac{1}{1+\omega^2} \quad h_- = \frac{\omega^2}{1+\omega^2}$$

$$F \begin{pmatrix} 1 & -\omega \\ \omega & 1 \end{pmatrix} = \begin{pmatrix} 1 & -\omega \\ \omega & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

~~the~~ $F \begin{pmatrix} 1 & -\omega \\ \omega & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 1 & -\omega \\ \omega & 1 \end{pmatrix}$

~~$F \varepsilon \begin{pmatrix} 1 & \omega \\ \omega & -1 \end{pmatrix} = \begin{pmatrix} 1 & -\omega \\ \omega & 1 \end{pmatrix}$~~

$$X = \begin{pmatrix} 0 & -\omega \\ \omega & 0 \end{pmatrix}$$

$$F \varepsilon \begin{pmatrix} 1 & \omega \\ -\omega & 1 \end{pmatrix} = \begin{pmatrix} 1 & -\omega \\ \omega & -1 \end{pmatrix}$$

$$F \varepsilon (1-X) = 1+X$$

$$\therefore F \varepsilon = \frac{1+X}{1-X}$$

" η " You want to understand clearly how to start from an orthog ~~graph~~ ^{repr} V, F, ε . Then double it to get something symplectic, then ~~graph~~ reduces using constraints to end up with a ~~graph~~ linear transf on V . Question:

Is there some sort of symplectic quotient in this construction? Generically V_+, V_- have the same dimension (canon iso?)

Is there a recipe to go from F, ε on V to a skew-symmetric linear transformation on V ? What about the C.T.?

Assume $\pm 1 \notin \text{spectrum of } g = F\varepsilon$. Then W should be the graph $\begin{pmatrix} 1 \\ T \end{pmatrix} V_+$ of an invertible operator $T: V_+ \xrightarrow{\sim} V_-$. One has $\varepsilon(1-X)$

$$F \begin{pmatrix} 1 & -T^* \\ T & 1 \end{pmatrix} = \begin{pmatrix} 1 & -T^* \\ T & 1 \end{pmatrix} \varepsilon \quad F(1+X) = (1+X)\varepsilon$$

$\Rightarrow F\varepsilon = \frac{1+X}{1-X}$ so the recipe ~~is~~ ^{should be} just the

inverse C.T. of $g = F\varepsilon$ $X = \frac{g-1}{g+1} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} g$

$$g = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} X = \frac{X+1}{-X+1} = \frac{1+X}{1-X}$$

~~graph~~

$$W \xrightarrow{\begin{pmatrix} 1 \\ T \end{pmatrix}} \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xrightarrow{(-T \ 1)} W^\perp$$

$$-T\hat{V}_c + \hat{V}_L = 0$$

$$\hat{I}_c + T^*\hat{I}_L = 0$$

$$\hat{I}_c = \hat{V}_c = s\hat{V}_c - V_c(0)$$

$$\hat{V}_L = \hat{I}_L = s\hat{I}_L - I_L(0)$$

$$s\hat{V}_c + T^*\hat{I}_L = V_c(0)$$

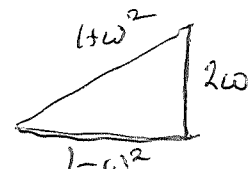
$$-T\hat{V}_c + s\hat{I}_L = I_L(0)$$

$$\left\{ s - \begin{pmatrix} 0 & -T^* \\ T & 0 \end{pmatrix} \right\} \begin{pmatrix} \hat{V}_c \\ \hat{I}_L \end{pmatrix} = \begin{pmatrix} V_c(0) \\ I_L(0) \end{pmatrix}$$

"0" Start with a fin. dim Euclidean space V equipped with two reflections F, ε . What's important is the decomposition of V into eigenspaces for the operator $\frac{g+g^{-1}}{2}$, the eigenvalues occurring are $\lambda \in [-1, 1]$, ~~but~~ you want to use the parametrization by ~~the~~ the variable $\omega \in [0, \infty]$. Relation between ω, λ ? $X = \begin{pmatrix} 0 & -\omega \\ \omega & 0 \end{pmatrix}$

$$g = \frac{1+X}{1-X} \quad g^{1/2} = \frac{1+X}{(1-X^2)^{1/2}} = \begin{pmatrix} 1 & -\omega \\ \omega & 1 \end{pmatrix} \frac{1}{\sqrt{1+\omega^2}} ?$$

$$\frac{1}{s-X} = \frac{s+X}{s^2-X^2} = \begin{pmatrix} s & -\omega \\ \omega & s \end{pmatrix} \frac{1}{s^2+\omega^2} \quad \text{that is}$$

~~straight~~ $F(1+X) = (1+X)\varepsilon$ $F\varepsilon = \frac{1+X}{1-X}$ 

$$\frac{1+X}{1-X} = \frac{(1+X)^2}{1-X^2} = \begin{pmatrix} 1-\omega^2 & -2\omega \\ 2\omega & 1-\omega^2 \end{pmatrix} \frac{1}{1+\omega^2} = \begin{pmatrix} \cos 2\theta & -\sin 2\theta \\ \sin 2\theta & \cos 2\theta \end{pmatrix}$$

where $\tan \theta = \omega$ ~~straight~~ Try again to get this $X = \begin{pmatrix} 0 & -\omega \\ \omega & 0 \end{pmatrix} \quad \omega \in \mathbb{R}$
 $g^{1/2} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ $g^{1/2} = \frac{1+X}{\sqrt{1+\omega^2}} =$

Start again with ~~two reflections~~ F, ε on V . Then $g = F\varepsilon$ is a rotation. Can you assign an angle to ~~the~~ g ?

~~To~~ To say $g = F\varepsilon$ is a rotation is probably meaningless. You have $SO(V) \subset O(V)$, where $SO(V)$ is connected - this is probably what you mean by a rotation. But then $\det(g) = \det(F)\det(\varepsilon)$ obviously depends on the number of signs (dims of ± 1 eigenspaces).

Look at $h = \frac{1}{2}(g+g^{-1})$ which is a symmetric operator on V commuting with F, ε whose spectrum $\subset [-1, 1]$. So there is an angle $\theta \in [0, \pi]$ such that $\cos \theta$ is the corresponding eigenvalue of h .

" L " Given F, ε on V you decompose V ~~into~~ into the eigenspaces V_λ , $\lambda \in \text{Spec}\{h = \frac{1}{2}(g+g^{-1})\}$. Here $-1 \leq \lambda \leq 1$. This is the basic decomposition to understand.

Discuss philosophy: You start with F, ε on V and pass to the Laplace transform ~~of~~ of 1st order linear constant coefficient D.E. on V , i.e. $e^{\pm X}$ where X is a ~~skew-symmetric~~ skew symmetric linear operator on V . Except there's degeneracy ~~where~~ where $X = \infty$ which needs to be understood. ~~where~~

Instead of $\lambda \in \text{Spec}\{h\} \subset [-1, 1]$ the natural parameter, eigenvalue type parameter, is ^{the} frequency ω . Actually the frequencies associated to X skew symmetric are of the form $\pm i\omega$. Instead of λ going from 1 to -1 you want ω , ~~or~~ or maybe ω^2 to go from 0 to $+\infty$ (or maybe s^2 should run from 0 to $-\infty$).

Let's get the relations ~~straight~~ straight using the idea that X should be the inverse Cayley transform $X = \frac{g-1}{g+1}$ when $g+1$ is invertible (i.e. $g \neq -1$). Thus you are ignoring ~~the frequency~~ $\omega = \infty$. You know that

~~where~~ $F\varepsilon = g = \frac{1+X}{1-X}$, where $X = \begin{pmatrix} 0 & -T^* \\ T & 0 \end{pmatrix}$

where $T: V_+ \rightarrow V_-$. To simplify suppose $V_\pm \cong \mathbb{R}$

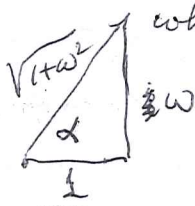
What is the ~~aim~~? You want to link the angles $\pm \theta$ associated to g to the frequencies $\pm \omega$ associated to the skew symmetric operator X .

Take $X = \begin{pmatrix} 0 & -\omega \\ \omega & 0 \end{pmatrix}$. Then $g = \begin{pmatrix} 1 & -\omega \\ \omega & 1 \end{pmatrix} \frac{1}{\sqrt{1+\omega^2}}$

$$K'' \quad X = \begin{pmatrix} 0 & -\omega \\ \omega & 0 \end{pmatrix} \quad g^{1/2} = \frac{1+X}{(1-X^2)^{1/2}} = \begin{pmatrix} 1 & -\omega \\ \omega & 1 \end{pmatrix} \frac{1}{(1+\omega^2)^{1/2}}$$

so $g^{1/2} = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$ where $\cos \alpha = \frac{1}{\sqrt{1+\omega^2}}$ $\sin \alpha = \frac{\omega}{\sqrt{1+\omega^2}}$

or $e^{i\alpha} = \frac{1+i\omega}{\sqrt{1+\omega^2}}$



$$g = \begin{pmatrix} \cos 2\alpha & -\sin 2\alpha \\ \sin 2\alpha & \cos 2\alpha \end{pmatrix} = \begin{pmatrix} \frac{1-\omega^2}{1+\omega^2} & -\frac{2\omega}{1+\omega^2} \\ \frac{2\omega}{1+\omega^2} & \frac{1-\omega^2}{1+\omega^2} \end{pmatrix}$$

~~Notice~~ Notice

that as ω goes from $-\infty$ to $+\infty$ then $e^{i\alpha}$ goes from $-i$ to $+i$

so $e^{2i\alpha}$ goes from -1 to -1 counterclockwise.

so things are not as nice as you would like.

$$\frac{g+g^{-1}}{2} = \frac{1}{2} \left(\frac{1+X}{1-X} + \frac{1-X}{1+X} \right) = \frac{1+X^2}{1-X^2} = \begin{pmatrix} 1-\omega^2 & \\ & 1-\omega^2 \end{pmatrix} \frac{1}{1+\omega^2}$$

$= \cos(2\alpha)$. It seems that the angles $\pm\theta$ associated to g , equivalently the eigenvalues $e^{\pm i\theta}$ of g , are "double" the angles $\pm\alpha$ belonging to $g^{1/2}$.

Notice: $g^{1/2} = \frac{1+X}{(1-X^2)^{1/2}}$ looks like the polar decomp of $1+X$. Also maybe $g_s^{1/2} = \frac{s+X}{(s^2-X^2)^{1/2}}$, for $s > 0$, but $g_s^{1/2}$ should be defined for $\forall s \notin \mathbb{R}_{\leq 0}$.

next idea might be to look at retracts again

$$W \xleftarrow{(\alpha_+^* \alpha_-^*)} \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{(\alpha_-^*)} W \quad \frac{\alpha_+^* \alpha_+^*}{h_+} + \frac{\alpha_-^* \alpha_-^*}{h_-} = 1_W$$

~~important idea~~ You can reconstruct V_+, V_- by canonical factorization of h_{\pm} $V_{\pm} = \text{completion of } W \text{ wrt } (\xi, h_{\pm})$.

λ'' Refresh memory about two retract cases

$$\textcircled{1} \quad W \xleftarrow{(\beta_+ \beta_-)} \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{\begin{pmatrix} \alpha_+ \\ \alpha_- \end{pmatrix}} W$$

\mathbb{C} retract of a $\mathbb{Z}/2$ graded module $h_{\pm} = \beta_{\pm} \alpha_{\pm}$
 $h_+ + h_- = W$

$$\textcircled{2} \quad \begin{pmatrix} W_+ \\ W_- \end{pmatrix} \xleftarrow{\begin{pmatrix} \beta_+ & 0 \\ 0 & \beta_- \end{pmatrix}} \begin{pmatrix} V \\ V \end{pmatrix} \xleftarrow{\begin{pmatrix} \alpha_+ & 0 \\ 0 & \alpha_- \end{pmatrix}} \begin{pmatrix} W_+ \\ W_- \end{pmatrix}$$

$p_{\pm} = \begin{pmatrix} \alpha_{\pm} & \beta_{\pm} \end{pmatrix}$ two projections on V

$$\begin{pmatrix} 0 & \beta_+ \alpha_- \\ \beta_- \alpha_+ & 0 \end{pmatrix} = \begin{pmatrix} \beta_+ & 0 \\ 0 & \beta_- \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \alpha_+ & 0 \\ 0 & \alpha_- \end{pmatrix}$$

$$\begin{pmatrix} W_+ \\ W_- \end{pmatrix} \xleftarrow{\begin{pmatrix} \beta_+ & 0 \\ 0 & \beta_- \end{pmatrix}} V \xleftarrow{\begin{pmatrix} \alpha_+ & \alpha_- \end{pmatrix}} \begin{pmatrix} W_+ \\ W_- \end{pmatrix}$$

Q: Would it be interesting to have $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ replaced by $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$? This would yield an odd skew symmetric operator on $\begin{pmatrix} W_+ \\ W_- \end{pmatrix}$.

Next project: To introduce random phases, to look for a new quantization for harmonic oscillators. Recall the idea. A harmonic oscillator is a Euclidean space V equipped with a non degenerate skew symmetric operator X . One has the polar decomp: $X = |X| J$ where $|X|$ gives the frequencies and $J^2 = -I$ is a complex structure on V . Quantization gives the bosonic Fock space $S_{\mathbb{C}} V$. Actually it's more subtle because of metaplectic symmetry, the $\frac{\omega}{2}$ ground state.

You should ^{make} a list of ideas.

- V real v.s. with pos. def symm. form and nondegenerate skew-symmetric form, i.e. V Euclidean space equipped with a skew adjoint operator X . V splits ^{orthogonal} into 2 planes invariant under X s.t. $X = \begin{pmatrix} 0 & -a \\ a & 0 \end{pmatrix}$ $0 \neq a$, $|a|$ frequency $|a|$

In case all frequencies are the same, then $O(2n)/U(n) =$ space of complex structures on $V =$ possible square roots of $-I$.

- V complex Hilbert, X non degenerate skew-hermitian. Here the possible phases are $J = iF$, $F = F^* = F^{-1}$. So $\coprod_{\alpha \leq p \leq n} \mathcal{G}_p(\mathbb{C}^n)$ is the space of phases.

- Building idea: $\{A \in \text{End}(V) \mid A = A^*, 0 \leq A \leq I\}$. Use the eigenvalues to make simplices parametrized by flags.

μ^n • Is there any link between the choice of $g^{1/2} = \frac{1+x}{(1-x^2)^{1/2}}$ and square roots of -1 . Notice that this form defines $g^{1/2}$ in terms of the polar decomposition of $1+x$. Similarly $g_s^{1/2} = \frac{s+x}{(s^2-x^2)^{1/2}}$ defined initially for $s > 0$, then extended analytically to $\mathbb{C} - \mathbb{R}_{\leq 0}$. These represent ~~the~~ variants of the ~~usual~~ polar decomposition recipe.

• Similarity between roots of an irreducible equation and random phases.

• Vague Idea. There seems to be a loss of information involved in passing from an irreducible orthogonal repr. of F, ε on \mathbb{R}^2 to the corresponding harmonic oscillator. The oscillator retains only positive type information, e.g. characteristic values, whereas quantization of the oscillator involves lifting to a double covering, that is, undoing the previous step in some way.

• Idea: Eliashberg rigidity thm: A C^0 convergent sequence of C^∞ symplectic transformations is C^∞ convergent. You might be able to use the C^∞ limit to prove decay. In the case $SL_2(\mathbb{R})$ elliptic elements converge to parabolic ones.

• Case $W = \begin{pmatrix} 1 \\ z \end{pmatrix} V_+$, $W^\perp = \begin{pmatrix} -\bar{z} \\ 1 \end{pmatrix} V_-$, the phase of z disappears after conjugation by an element centralizing ε .

• It might be useful to have a clean version of the ^{the} representation theory (orthogonal, unitary) of $\langle F, \varepsilon \rangle$, ~~before~~ ^{the} looking at phases ~~random~~. (Do you want $|\sin \theta|$?). Key point is that the endo ring of the ^{irred} representation is $\mathbb{R}(\mathbb{C})$, because the group ring maps ^{Bass} onto all operator on the irred. repr.

• χ function of a graph $\stackrel{?}{=}$ char poly of some correspondence maybe from a Kronecker module. Something related to fix points of iterates. Examples from geodesic flows?

Let's try to get the F, ε representation into a canonical form. Fix $\cos \theta \in (-1, 1)$. Then the standard form ~~should be~~ to try is

$$g = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \quad \varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \begin{array}{l} \text{on } \mathbb{R}^2 \\ \text{on } \mathbb{C}^2 \end{array}$$

This is an irred ~~orth~~ unitary repr.

Something's wrong here because changing θ to $-\theta$ ~~leaves~~ leaves the eigenvalues $\cos \theta$, your invariant for the representation unchanged.

So try ^{indexing} the repr by $0 < \theta < \pi$.

You have $G = \langle F, \varepsilon \rangle = \varepsilon \times g \longrightarrow \text{End}(\mathbb{R}^2)$

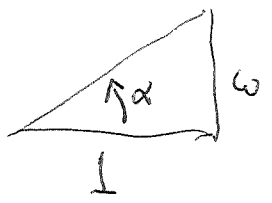
It should be clear that changing g_θ to $g_{-\theta}$ yields an ~~isomorphic~~ isomorphic repr., isom being given by ε . But $g_{-\theta}$ is not on the list $0 < \theta < \pi$.

So now where are we? ~~isomorphic~~

Take Inv. C.T.

$$g^{1/2} = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} \quad \alpha = \frac{\theta}{2} \quad 0 < \alpha < \frac{\pi}{2}$$

$$= \begin{pmatrix} 1 & -\tan \alpha \\ \tan \alpha & 1 \end{pmatrix} \begin{array}{l} \cos \alpha \\ \cos \alpha \end{array}$$

$$= \begin{pmatrix} 1 & -\omega \\ \omega & 1 \end{pmatrix} \frac{1}{\sqrt{1+\omega^2}}$$


$$g^{1/2} = \frac{1+X}{(1-X^2)^{1/2}}$$

so there is a different angle α around, present.

" ξ " What is the inverse C.T.? ~~g~~ $g \mapsto \frac{g-1}{g+1} = X$

This is how one gets the harmonic oscillator associated to a representation F, ε . Assume $g+1$ invertible define X by ~~g~~ $\frac{1+X}{1-X} = g = \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} X$, so that $X = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} g = \frac{g-1}{g+1}$. Then $X^* = \frac{g^{-1}-1}{g^{-1}+1} = -\frac{g-1}{g+1} = -X$ so X is skew-symmetric yielding the 1-parameter grp of orthogonal transf. $\exp(tX)$ with L.T. $= (S-X)^{-1}$.

Now you want to relate the parameters in the F, ε representation, i.e. the angle $\theta \in (0, \pi)$, to the frequency parameter ω , for the corresponding s.h.o. ~~g~~ So consider $g = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$, $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \text{ on } \mathbb{R}^2$ Let $X = \begin{pmatrix} 0 & -\omega \\ \omega & 0 \end{pmatrix}$ be the C.T. of g . One has

$$g^{1/2} = \frac{1+X}{(1-X^2)^{1/2}} = \begin{pmatrix} 1 & -\omega \\ \omega & 1 \end{pmatrix} \frac{1}{\sqrt{1+\omega^2}} = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$$

where $\frac{\sqrt{1+\omega^2}}{\omega} \uparrow \alpha$. ~~g~~ It seems that you want ω to range $-\infty < \omega < \infty$, $\omega = \tan \alpha$ $-\frac{\pi}{2} < \alpha < \frac{\pi}{2}$.

Of course $\theta = 2\alpha$. ~~g~~

~~g~~ Strange situation: On one side you have an orthogonal (or unitary) rep. of $\langle F, \varepsilon \rangle$ which yields naturally the angles $\pm \theta$, spectrum of the orthogonal transf. $g = F\varepsilon$. The eigenvalues of $g = \frac{1+X}{1-X}$. On the other side you have a skew-symmetric operator X with the eigenvalues $\pm i\omega$, where $\omega = \tan \alpha$ and $\theta = 2\alpha$.

You still ~~want~~ want to explain $\frac{S^2 + \omega^2}{S(1+\omega^2)} = S \cos^2 \alpha + S^{-1} \sin^2 \alpha$

0" • Problem of forced harmonic oscillators. There should be no problem for the case of an arbitrary forcing term which is a function of time with values in the space of dominant variables, e.g. applied voltage source in series with a capacitor, applied current source in series with an inductor. This situation encountered in Thevenin theory (each edge a pure emf in series with an internal resistance)

Let's look for evidence that quantization of a harmonic oscillator involves ~~undoing~~ undoing a squaring process.

Begin by defining a harmonic oscillator to be an orthogonal representation of $\langle F, \varepsilon \rangle$. Then you have natural angles arising $e^{\pm i\theta}$, the eigenvalues of $g = F\varepsilon$. These are natural phases from the representation viewpoint.

Next consider the classical time evolution which is given by the inverse C.T. X of g . The eigenvalues of X give the frequencies of the time evolution. What's natural?

Strange. $\langle F, \varepsilon \rangle \rightsquigarrow \text{Spectrum } \{e^{\pm i\theta}\}$
 Spectrum $\{\pm i\omega\}$ of X where $\omega = \tan \alpha$ $\alpha = \frac{\theta}{2}$
 $-\frac{\pi}{2} < \alpha < \frac{\pi}{2}$

~~So far you have studied~~ So far you have studied the classical mechanics of a ^{connected} LC network. You have ended up with a standard "Hamiltonian" picture namely a Euclidean v.s. + skew-symmetric operator X .

The LC network seems to ~~introduce~~ introduce the symplectic structure naturally. The states ~~space~~ are voltages + currents which are naturally dual geometrically: cochains (electrical) + chains (magnetic), and physically dual via the power pairing.

Consider a mechanical harmonic oscillator with two energy types kinetic + potential; $\frac{1}{2} \dot{q}^t m \dot{q}$, $\frac{1}{2} q^t k q$; functions of velocity + position. Then comes the mystery

ρ'' perturbation on Fock space as you go from $t = -\infty$ to $t = +\infty$ is a translation, $\int_{-\infty}^{\infty} dt$ which probably amounts the time integral of the ~~translation~~ path in the translation plane, plus some phase, which might have an interpretation as a determinant.

The hope is this ~~time~~ time dependent perturbation picture will illuminate the forced oscillator situation. Let's see if you put into words what might happen. You consider a s.h.o. What is this? Classically it is given by a real 2-plane equipped with a pos. def. symmetric form and a non-deg symplectic form. Another version: A Euclidean 2-plane equipped with an invertible skew-symmetric operator X . Apply polar decomp. $X = |X|J$ to get the frequency $\omega = |X|$ and complex structure. Question: ~~Does~~ Does this V, X yield a representation of $\langle F, \varepsilon \rangle$ on V ?

So it seems possible, likely, that a harmonic oscillator: Euclidean space V + invertible skew-symmetric operator X is a different object than an orthogonal representation of $\langle F, \varepsilon \rangle$ the ∞ dihedral gp on V .

Repeat. Define a harm. osc. to be a Euclidean space V equipped with a skew-symmetric (invertible) operator X . Use polar decomp. $X = |X|J$ to split (V, X) into orthogonally according to the ^{positive} eigenvalues ω of $|X|$. These eigenspaces have natural complex structures. This reduces to the case where $|X| = \omega > 0$, i.e. a harm osc. with a single frequency.

5" Where are you? You are ~~studying~~ studying a general harmonic oscillator and have used the eigenspaces of $|X|$ to split the oscillator into ones with a single frequency. So you've reduced to $X = \omega J$, where $J^2 = -1$ and $\omega > 0$.

Q: What can you say about $g = \frac{1+X}{1-X}$? This is something else you've forgotten about: the ungraded cases.

So now you ~~might see~~ how a harmonic oscillator (V, X) might not arise from an orth repr of $\langle F, \varepsilon \rangle$ on V .

Look at $V = \mathbb{R}^2$ with $X = \begin{pmatrix} 0 & -\omega \\ \omega & 0 \end{pmatrix}$. Then $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ and $F = g\varepsilon = \frac{1+X}{1-X} \varepsilon$ give the repr. you want.

Conj: Given (V, X) a harm. osc. it should be possible (because of X invertible) to find an ε on V such that $\varepsilon X \varepsilon = -X$.

Idea: Is there a role in all this harmonic oscillator stuff, with its symplectic background, for a contact structure

Review $\mathbb{Z}/2$ graded module $\begin{pmatrix} W_+ \\ W_- \end{pmatrix}$ retract of free $\mathbb{Z}/2$ gr mod $\begin{pmatrix} V \\ V \end{pmatrix}$

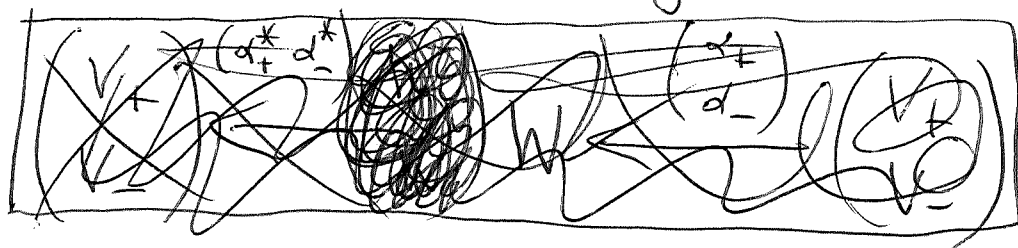
$$\begin{pmatrix} W_+ \\ W_- \end{pmatrix} \xleftarrow{\begin{pmatrix} \beta_+ & \beta_- \end{pmatrix}} \begin{pmatrix} V \\ V \end{pmatrix} \xleftarrow{\begin{pmatrix} \alpha_+ & \alpha_- \end{pmatrix}} \begin{pmatrix} W_+ \\ W_- \end{pmatrix} \quad \beta_{\pm} \alpha_{\pm} = 1_{W_{\pm}} \quad P_{\pm} = \alpha_{\pm} \beta_{\pm} \quad \text{two proj on } V.$$

$$X = \begin{pmatrix} \beta_+ & 0 \\ 0 & \beta_- \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \alpha_+ & 0 \\ 0 & \alpha_- \end{pmatrix} = \begin{pmatrix} 0 & \beta_+ \alpha_- \\ \beta_- \alpha_+ & 0 \end{pmatrix} \quad \text{odd op on } W$$

$$\begin{pmatrix} W_+ \\ W_- \end{pmatrix} \xleftarrow{\begin{pmatrix} \beta_+ \\ \beta_- \end{pmatrix}} V \xleftarrow{\begin{pmatrix} \alpha_+ & \alpha_- \end{pmatrix}} \begin{pmatrix} W_+ \\ W_- \end{pmatrix} \quad V = \text{Im} (1_W + X)$$

" \bar{L} " The idea would be to produce an oscillator type structures. X defined as compression in $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ is symmetric. You could make ~~it~~ skew symmetric X by compressing $\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ $\begin{pmatrix} 1 & -\alpha_+^* \alpha_- \\ \alpha_-^* \alpha_+ & 1 \end{pmatrix}$

I can't tell if this is interesting; it might help ~~you~~ to interchange W and V .



$$\begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{\begin{pmatrix} \alpha_+^* & 0 \\ 0 & \alpha_-^* \end{pmatrix}} \begin{pmatrix} W \\ W \end{pmatrix} \xleftarrow{\begin{pmatrix} \alpha_+ & \\ & \alpha_- \end{pmatrix}} \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$$

$$X = \begin{pmatrix} \alpha_+^* & 0 \\ 0 & \alpha_-^* \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \alpha_+ & 0 \\ 0 & \alpha_- \end{pmatrix} = \begin{pmatrix} 0 & -\alpha_+^* \alpha_- \\ \alpha_-^* \alpha_+ & 0 \end{pmatrix}$$

$$\begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{\begin{pmatrix} \alpha_+^* \\ \alpha_-^* \end{pmatrix}} W \xleftarrow{\begin{pmatrix} \alpha_+ & \alpha_- \end{pmatrix}} \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$$

$\begin{pmatrix} 1_+ & \alpha_+^* \alpha_- \\ \alpha_-^* \alpha_+ & 1_- \end{pmatrix}$ not $1+X$

Perhaps conj by $\begin{pmatrix} 1 & \\ & i \end{pmatrix}$ to? NO.

If X is as above, then you have ~~the~~ $1 \pm X$ invertible, so you have a C.T. but meaning not clear.

"u"
 between a ^{general} harmonic oscillator and an orth. repr. of $\langle F, \varepsilon \rangle$ namely the latter is a $\mathbb{Z}/2$ -graded version of the former. Recall defn. Harm. osc. is a Euclidean space V equipped with invertible skewsymmetric X . In the $\mathbb{Z}/2$ graded version $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ is equipped with ε grading and X is odd $\varepsilon X \varepsilon = -X$. The C.T. $g = \frac{1+X}{1-X}$ is ~~only~~ an orthogonal transf. ~~in~~ in the "odd" case and $\varepsilon g \varepsilon^{-1} = g^{-1}$ in the "even" case.

Question: To what does $H = \frac{p^2}{2m} + \frac{k}{2} q^2$ & symplectic volume ~~belong~~ belong? The flow is $\dot{q} = \frac{p}{m}, \dot{p} = -kq$

so $X = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix}$ $-X^2 = \begin{pmatrix} +m^{-1}k & 0 \\ 0 & -km^{-1} \end{pmatrix}$ $|X| = \begin{pmatrix} \omega & 0 \\ 0 & \omega \end{pmatrix}$
 with $\omega = \sqrt{\frac{k}{m}}$, $J = \begin{pmatrix} 0 & \frac{1}{m\omega} \\ -\frac{k}{\omega} & 0 \end{pmatrix}$ $\frac{k}{\omega} = k \sqrt{\frac{m}{k}} = \sqrt{km}$
 $\frac{1}{m\omega} = \frac{1}{m \sqrt{\frac{k}{m}}} = \frac{1}{\sqrt{km}}$

$$H = \frac{p^2}{2m} + \frac{k}{2} q^2 = \underbrace{\begin{pmatrix} -\frac{ip}{\sqrt{2m}} \\ \frac{\sqrt{k}}{2} q \end{pmatrix}}_{A^*} \underbrace{\begin{pmatrix} \frac{ip}{\sqrt{2m}} \\ \frac{\sqrt{k}}{2} q \end{pmatrix}}_A + \text{const}$$

$$A^* A = H + \underbrace{\begin{bmatrix} -\frac{ip}{\sqrt{2m}} & \frac{\sqrt{k}}{2} q \end{bmatrix}}$$

$$\frac{1}{2} \sqrt{\frac{k}{m}} [-ip, q] = \frac{1}{2} \omega (-i) \frac{\hbar}{i} = -\frac{1}{2} \hbar \omega$$

$$H = A^* A + \frac{1}{2} \hbar \omega \quad \cancel{[A, A^*]} [A, A^*] = \hbar \omega$$

$\dot{x} = Ax + Bu, y = Cx + Du, H(s) = C \frac{1}{s-A} B + D$
^{transfer fn.}
 x internal state variables, $u = \text{input}, y = \text{output}$

φ'' Question: Can you put ~~the~~ mechanical harmonic oscillator into $\mathbb{Z}/2$ graded form? This should be clear from orthogonal decomposition of (V, X) into 2 planes, where X becomes $\begin{pmatrix} 0 & -\omega \\ \omega & 0 \end{pmatrix}$. This ~~idea~~ deserves ~~a~~ careful study, to see the ~~possible~~ possible choices.

~~IDEA~~ IDEA: Review the Artin-Schreier theory of real closed fields, especially Sturm sequences, which are used to calculate the number of ^{real} roots.

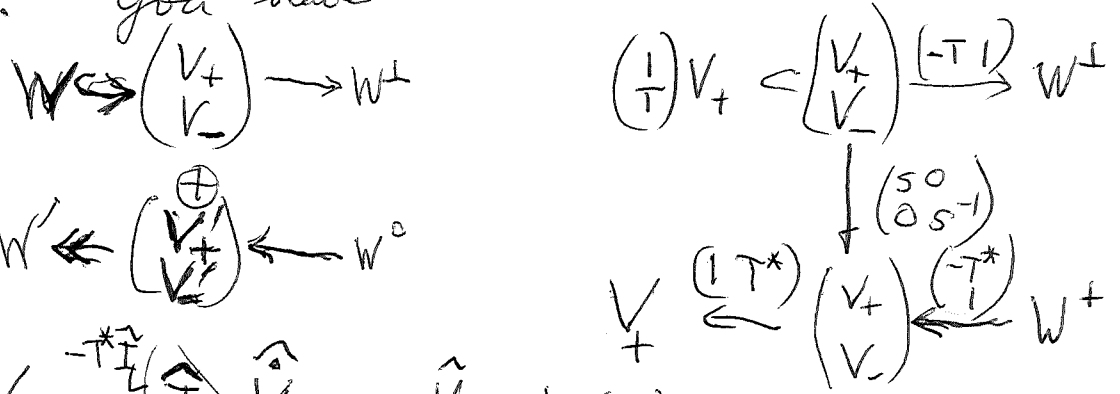
Yesterday you found, ^{recalled} a viewpoint for the quantum forced harmonic oscillator. Classically ~~the forcing term~~ the forcing term ~~is~~ can be any point of phase space depending on time and the motion is ^(given by solving) $\begin{pmatrix} \dot{q} \\ \dot{p} \end{pmatrix} - X \begin{pmatrix} q \\ p \end{pmatrix} = f(t)$ ($f(t)$ forcing term).

Quantum mechanically you probably need to solve this D.E. in the Heisenberg group.

It ought to be interesting to solve this DE using the L.T. ~~It's not~~ ^{immediately} clear what this means.

What do you have? A phase space \mathbb{R}^2 with skew symmetric operator X giving the time evolution classically. You're given a forcing term which is a smooth path in the phase space with compact support. Maybe the standard way to study this is the time dependent scattering theory. Compare incoming to outgoing. ??

"X" Let's try to understand a bit about whether a mechanical oscillator $\frac{1}{2}p^t m^{-1} p + \frac{1}{2}q^t k q$ has a natural $\mathbb{Z}/2$ -grading. Try simple case $\frac{p^2}{2m} + \frac{kq^2}{2}$. Compare with LC case. Can you really describe what's happening. In the LC case you have the puzzle of the symplectic quotient preceding the state space. You have



$$TV_C = V_L \xrightarrow{-T^* I_C} \hat{I}_C = \hat{V}_C = s \hat{V}_C - V_C(0)$$

$$I_C + T^* I_L = 0 \quad \hat{V}_L = \hat{I}_L = s \hat{I}_L - I_C(0) \quad \begin{pmatrix} s & T^* \\ -T & s \end{pmatrix} \begin{pmatrix} \hat{V}_C \\ \hat{I}_L \end{pmatrix} = \begin{pmatrix} V_C(0) \\ I_L(0) \end{pmatrix}$$



still confusing, however, you have this ~~stuff~~ cut down to a symplectic quotient of dim e. This looks strange because e doesn't look even, but if $X = \begin{pmatrix} 0 & -T^* \\ T & 0 \end{pmatrix}$ is assumed nondegenerate then it's clear.

symplectic stuff
On the surface phase space of dim 2e. This doesn't look even, but if nondegenerate then it's clear.

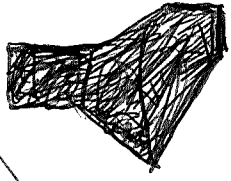
Look at $H = \frac{1}{2} p^t m^{-1} p + \frac{1}{2} q^t k q$

$$\dot{q} = \frac{\partial H}{\partial p} = m^{-1} p \quad \dot{p} = -\frac{\partial H}{\partial q} = -kq$$

This should fit into the LC scheme.
 $\ddot{q} = m^{-1} \dot{p} = m^{-1}(-k)q$
 $\ddot{q} + (m^{-1}k)q = 0$
 $m\ddot{q} = -kq$ Newton

$$\psi'' \quad X = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix} \quad \begin{pmatrix} \dot{q} \\ \dot{p} \end{pmatrix} = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$$

$$H = \frac{p^2}{2m} + \frac{1}{2}kq^2 = \frac{1}{2} \begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$$



$$\int \int A \{ \} = \int \int H X \{ \}$$

$$A = HX^{-1} = \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix}^{-1} ?$$

A, H are bilinear forms, maps $V \xrightarrow[A]{H} V^*$

so X is either $A^{-1}H$ or $H^{-1}A$

symmetric S : $V \rightarrow V^*$
 antisymm A

You want $AX = H$

phase space

$$A = HX^{-1} = \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix}^{-1}$$

$$= \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} 0 & -k^{-1} \\ m & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$$

What do you want? To see this is the same as what you got from an LC oscillator.



$$X = \begin{pmatrix} 0 & -T^* \\ T & 0 \end{pmatrix}$$

$$\begin{aligned} AX = H &= H^t = x^t A^t = -x^t A \\ HX = A &= A^t = -x^t A^t = -x^t H \end{aligned}$$

$$H = \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix}$$

$$X = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix}$$

$$V \xrightarrow[A]{H} V^*$$

$$AX = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix} = \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix}$$

$$AX = H$$

X respects the symplectic form A:
 symmetric form H:

Verify that

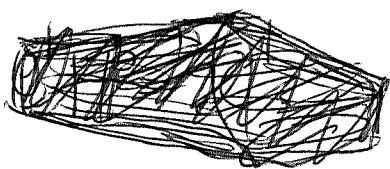
$$\begin{aligned} X^t A + A X &= 0 \\ X^t H + H X &= 0 \end{aligned}$$

ω'' Next you want to change to orthonormal bases in the position & momentum spaces. This means writing $k = \cancel{\text{matrix}} k^t k$, i.e. $g^t k g = (k_g)^t (k_g)$, simplest choice is $k^{1/2}$, pos. sqrt. It should be true that $K = g k^{1/2}$ where g is an arbitrary orthogonal matrix.

Do the same in momentum space $m^{-1} = (\mu^{-1})^t (\mu^{-1})$ where $\mu^{-1} = g m^{-1/2}$, g arb. orth. Take

simplest choices and change vbls. $g = \cancel{\text{matrix}} k^{-1/2} Q$ so that $g^t k g = Q^t k^{1/2} k k^{-1/2} Q = Q^t Q$. from pt

$p = m^{+1/2} P$ so that $p^t m^{-1} p = p^t m^{+1/2} m^{-1} m^{+1/2} P = P^t P$.



$$\begin{pmatrix} Q \\ P \end{pmatrix}^t \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} Q \\ P \end{pmatrix} = Q^t Q + P^t P$$

Now what? You've made a transf. of coords. from $\begin{pmatrix} g \\ p \end{pmatrix}$ to $\begin{pmatrix} Q \\ P \end{pmatrix}$ which simplifies H , but should make A harder to understand.

$$A = \begin{pmatrix} g_1 \\ p_1 \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} g_2 \\ p_2 \end{pmatrix} \quad \begin{pmatrix} g \\ p \end{pmatrix} = \begin{pmatrix} k^{-1/2} & 0 \\ 0 & m^{1/2} \end{pmatrix} \begin{pmatrix} Q \\ P \end{pmatrix}$$

$$A = \begin{pmatrix} Q_1 \\ P_1 \end{pmatrix}^t \begin{pmatrix} k^{-1/2} & 0 \\ 0 & m^{1/2} \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} k^{-1/2} & 0 \\ 0 & m^{1/2} \end{pmatrix} \begin{pmatrix} Q_2 \\ P_2 \end{pmatrix}$$

$$= \begin{pmatrix} Q_1 \\ P_1 \end{pmatrix}^t \begin{pmatrix} 0 & -k^{-1/2} m^{1/2} \\ m^{1/2} k^{-1/2} & 0 \end{pmatrix} \begin{pmatrix} Q_2 \\ P_2 \end{pmatrix} \quad \left(\frac{k}{m}\right)^{1/2} = \omega$$

$$A X = H \quad X = A^{-1} H = \begin{pmatrix} 0 & -m^{-1/2} k^{1/2} \\ -m^{-1/2} k^{1/2} & 0 \end{pmatrix} I$$

\int_0 $X = \begin{pmatrix} 0 & m^{-1/2} k^{1/2} \\ -m^{-1/2} k^{1/2} & 0 \end{pmatrix}$ like $X = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix}$

There's a problem about $m^{1/2}$, $k^{1/2}$: What do these mean?
 $m, k: V \rightarrow V^*$ are symm bilinear forms
 so $m^{-1}k$, $k^{-1}m$ are well defined autos of V .

Review: $H = \frac{1}{2} p^t m^{-1} p + \frac{1}{2} q^t k q$ Hamilton. fu.

Ham. eqns $\dot{q} = \frac{\partial H}{\partial p} = m^{-1} p$ $\dot{p} = -\frac{\partial H}{\partial q} = -k q$

~~and~~ m, k are pos. def symm bil. forms on p -space and q -space resp. They yield kin + pot energy resp.

The Ham flow is a linear operator X on phase space

$$X = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix} \text{ means } \begin{pmatrix} \dot{q} \\ \dot{p} \end{pmatrix} = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$$

V is phase space which splits into V_+ q -space and V_- p -spaces. So $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ is a polarized Euclidean space. What is subtle is the fact

that position + momentum spaces are naturally dual.

Stop. Return to abstract ham. osc. situation

Phase space V equipped with H pos. def symm. $V \rightarrow V^*$
 A nondeg skewsym $V \rightarrow V^*$

~~Define~~ $H = AX$ defines the Hamiltonian flow on V . i.e. $X = A^{-1}H$. Facts $\begin{pmatrix} X^t A + A X = 0 \\ X^t H + H X = 0. \end{pmatrix}$

$AX = H = H^t = X^t A^t = -X^t A \implies X$ skewsym of V equipped with quad form X .
 $\left(\begin{matrix} HX = AX \\ XH = -X^t A X = -X^t H \end{matrix} \right)$

This is the ungraded case. You want to believe that this X is somehow related to a more interesting orthogonal transf. g via C.T.

g''' Show $m^{-1}k$ symmetric wrt $g^t k g'$
 ~~$(m^{-1}k g')^t k g' = g^t k (m^{-1}k g')$~~

$$(m^{-1}k g')^t k g' = g^t k (m^{-1}k g')$$

$$(k m^{-1} p)^t m^{-1} p' = p'^t m^{-1} (k m^{-1} p') \quad \text{YES}$$

check X skew symm wrt H

$$\begin{pmatrix} g \\ p \end{pmatrix}^t \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix} \begin{pmatrix} g' \\ p' \end{pmatrix} \stackrel{?}{=} \left(\begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix} \begin{pmatrix} g \\ p \end{pmatrix} \right)^t \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} g' \\ p' \end{pmatrix}$$

$$\begin{pmatrix} 0 & k m^{-1} \\ -m^{-1} k & 0 \end{pmatrix} = \begin{pmatrix} g \\ p \end{pmatrix} \begin{pmatrix} 0 & -k \\ m^{-1} & 0 \end{pmatrix} \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} g' \\ p' \end{pmatrix}$$

~~different sign~~

$$\begin{pmatrix} 0 & -k m^{-1} \\ m^{-1} k & 0 \end{pmatrix}$$

m^{-1}, k are pos. def. symm. bilinear forms. Gram-Schmidt process gives orth basis. \odot Choose a ~~basis~~ v_1, \dots, v_n basis $e_1, \dots, e_n \in V_+$ then use GS process. This amounts

$GL_n \mathbb{R} = O_n \times T_n$. Start with k pos. def ^{symm.} matrix i.e. make \mathbb{R}^n into a Eucl. space via $g^t k g$. Then

~~Let~~ Let $g \in GL_n(\mathbb{R})$ be ~~another~~ ~~a~~ change another basis, the columns are orthonormal.

$v_1, \dots, v_n \in \mathbb{R}^n$ col. vectors

$$v_i^t k v_j = \delta_{ij} \quad g = (v_1, \dots, v_n)$$

$$g^t k g = I_n \quad \text{or} \quad k = (g^{-1})^t g^{-1}$$

δ''' Let $k: V \rightarrow V^*$ be pos. def. symm.
 Then you get a pos. inner product $g^t k g$ on V
 You had some idea about $k^{1/2}$ which doesn't
 make sense probably. The idea ~~involves~~
 constructing $k = k^t k$.

Start again with $H = \frac{1}{2} p^t m^{-1} p + \frac{1}{2} g^t k g$, the
 Hamiltonian fn. on phase space of $\begin{pmatrix} q \\ p \end{pmatrix} \in \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$.

Hamilton's eqns. of motion:

$$\dot{q} = \frac{\partial H}{\partial p} = m^{-1} p \quad \dot{p} = -\frac{\partial H}{\partial q} = -k g$$

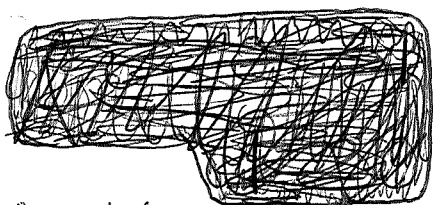
so the infinitesimal generator of the motion is
 linear transformation

$$X \begin{pmatrix} q \\ p \end{pmatrix} = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$$

X is an odd linear transf. on phase space

$$H = \begin{pmatrix} m^{-1} & 0 \\ 0 & k \end{pmatrix} : \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \longrightarrow \begin{pmatrix} V_+^* \\ V_-^* \end{pmatrix}$$

H is an even symmetric bilinear form on phase space



WAIT;

For X to be defined you
 have to interpret k as a map
 $k: V_+ \rightarrow V_-$ and m^{-1} as a map $m^{-1}: V_- \rightarrow V_+$

which means that you need to identify
 V_- with V_+^* and V_+ with V_-^*

$p q$

$g \frac{cm^2}{sec^2} sec$

$erg sec$

$\exp \frac{i t H}{\hbar}$

ε''' try to understand better duality between

position + momentum

g, p

$\text{cm } g \frac{\text{cm}}{\text{sec}} = \text{erg sec}$

Repeat. mechanical oscillator. phase space = $\begin{pmatrix} V_+ \\ V_- \end{pmatrix} \ni \begin{pmatrix} q \\ p \end{pmatrix}$

Important fact is that V_+, V_- are ^{naturally} in duality which means you are given a pairing $g, p \mapsto g^t p$

$$V_+ \xrightarrow{\sim} V_-^*$$

$$(g, p) \mapsto g^t p$$

also

$$V_- \xrightarrow{\sim} V_+^*$$

$$g \mapsto (p \mapsto g^t p) \quad ?$$

$$p \mapsto (g \mapsto p^t g)$$

So what? What did you learn? Phase space is $\begin{pmatrix} V_+ \\ V_+^* \end{pmatrix}$. Now $k: V_+ \xrightarrow{\sim} V_+^*$??

As usual you're confused by symplectic stuff!

~~Apparently~~ Apparently what happens is that V_+ and V_- are related by duality, so $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ is naturally symplectic. ~~But you have pos def.~~ On

V you have 2 structures A, H

$$A: V \longrightarrow V^* \quad \text{anti symm.}$$

$$H: V \longrightarrow V^* \quad \text{symm pos}$$

Review ~~_____~~ In the LC case you start with a representation of the dihedral group $\langle g, \varepsilon \rangle$ and obtain the time evolution of the network from the Inv.C.T. X of g , which is a skew symm operator odd wrt ε : $\varepsilon X \varepsilon^{-1} = -X$.

§ⁱⁱⁱ ~~There~~ There is an ungraded version of the preceding repr of $\langle g, \varepsilon \rangle$, where you start with an orthogonal transf g and obtain the time evolution of a harmonic oscillator from the ICT X of g .

In both of these cases one should assume that $-1 \notin \text{sp}(g)$, so that X is well-defined, and also that $1 \notin \text{sp}(g)$, so that X is invertible.

Now ~~you~~ look at a "mechanical" harmonic oscillator. This means you have a phase space $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ which is the direct sum of position space V_+ and ~~momentum space~~ momentum space V_- , which are ~~equipped~~ equipped with a duality pairing, allowing one to define the symplectic form

$$\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix} = -q^t p' + p^t q'$$

$$p^t q = q^t p$$

Finally you are given the Hamiltonian which is the symmetric bilinear form

$$\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix}$$

the direct sum of the potential energy on position space and the kinetic energy on momentum space (up to ε).

The question now is whether the mechanical harm. oscillator is $\mathbb{Z}/2$ graded. ~~This~~ This seems true because

the ~~anti~~ symmetric form $A = \begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix}$ is odd wrt $\varepsilon \begin{pmatrix} q \\ p \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix} = \begin{pmatrix} q \\ -p \end{pmatrix}$

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\therefore \varepsilon A = -A \varepsilon$$

η^n Also $H = \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix}$ is even and
 so $X = A^{-1}H = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix}$

is odd. ~~odd~~

~~harmonic~~ mech. oscillator, phase space = pos. space \oplus mom. space
~~oscillator~~ $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$, equipped with a duality isom.

~~oscillator~~ $V \times V \rightarrow \mathbb{R}$

$\begin{pmatrix} q \\ p \end{pmatrix}, \begin{pmatrix} q' \\ p' \end{pmatrix} \mapsto q^t p' + p^t q'$

~~is its~~ notation confused. $V_+ \times V_- \rightarrow \mathbb{R}$
 $(q, p) \mapsto q^t p$. What is a dual pair P, A, Q

P right A -module pairing $(q, p) \mapsto \langle q, p \rangle$ bilinear
 Q left A -module $\langle q, p \rangle$ bilinear

$q^t p$ notation OK when thinking of p, q as column vectors. One has $q^t p = p^t q$. Ideally, you would like to have maps:

$\mathbb{R} \xrightarrow{q} V_+, \mathbb{R} \xrightarrow{p} V_-$

~~oscillator~~ $\mathbb{R} \xleftarrow{q^t} V_+^* = V_- \xleftarrow{p} \mathbb{R}$

Then you have OK $\mathbb{R} \xleftarrow{p^t} V_+^* = V_- \xleftarrow{q} \mathbb{R}$

H symmetric bil form $\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$
 Hamiltonian fn. $\frac{1}{2} p^t m^{-1} p + \frac{1}{2} q^t k q$

A anti-symm. nondeg $\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix} = -q^t p' + p^t q'$

$AX = H \quad X = A^{-1}H = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix}$

$\begin{pmatrix} \dot{q} \\ \dot{p} \end{pmatrix} = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$
 $\dot{q} = m^{-1} p$
 $\dot{p} = -k q$

0''

~~Question. This should consist of a Hilbert space~~

Now that you have a \mathbb{Z}_2 -grading on the mechanical harmonic oscillator you ^{want} to choose ~~an~~ orth bases for V_+, V_- . You want $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ to be just a polarized Euclid. space. You ^{want to} make H standard. ~~and~~

$$\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix} = q^t k q' + p^t m^{-1} p' \stackrel{?}{=} Q^t Q + P^t P$$

linear change of variable $Q = g q$ $Q^t Q = g^t g^t g g$

$$g^t g = k. \quad \text{sim } P = h p \quad P^t P = p^t h^t h p = p^t m^{-1} p$$

$h^t h = m^{-1}$. The problem here is that you have ~~not~~ not respected the duality between V_+ and V_- ,

which is given by $P^t q = P^t (h^t)^{-1} g^{-1} Q$ $T^t = (g^t)^{-1} h^{-1}$
 $g^t p = Q^t (g^t)^{-1} h^t P$ $T = (h^t)^{-1} g^{-1}$

Duality is $P^t q = P^t T^t Q$
 $g^t p = Q^t T P$

$$A = \begin{pmatrix} g \\ p \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix} = -g^t p' + p^t q'$$
$$= -Q^t T p' + P^t T^t Q' = \begin{pmatrix} Q \\ P \end{pmatrix}^t \begin{pmatrix} 0 & -T^t \\ T & 0 \end{pmatrix} \begin{pmatrix} Q' \\ P' \end{pmatrix}$$

This should be X as you know sign wrong as $X = A^{-1} H = A^{-1}$

Pretty idea. von Neumann used the C.T. to construct the ~~time~~ operator on Hilbert space generating time evolution (also translation in position, momentum). You have been looking at time evolution for a harmonic oscillator, a free particle situation, but still you need C.T. to handle time it seems.

i'''' Next you want an ungraded version. You would like ~~something~~ descent to appear. Start with Euclidean space + invertible skew symmetric operator X .

Maybe this ~~point~~ point of departure is unwise, since all you can think of doing is polar decomp. of X , leading to the usual positive frequencies + complex structure J .

Example of descent maybe ~~for~~ $\mathbb{R} \rightarrow \mathbb{C}$ that you have encountered; $J^2 = -1$. Start with V ~~Euclidean~~ $\dim 2n$, then the space of complex structures is $O(2n)/U(n)$, and if V Hilbert $\dim \infty$ then $J^2 = -1$ same as $F^2 = 1$, so you get full $Grass(V)$.

Other idea. To ~~define~~ define symplectic vector space using the hyperbolic construction $\begin{pmatrix} V \\ V^* \end{pmatrix}$, like Groth defines \mathcal{A} -rings.

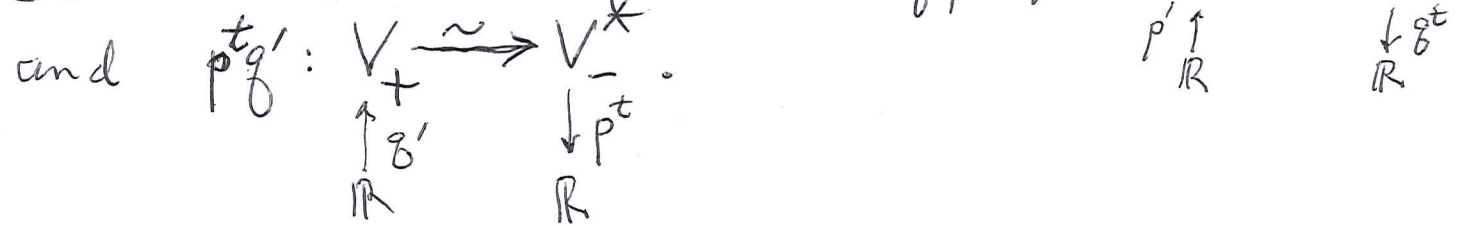
~~Let~~ Let V_+ be a f.d. vector space with dual V_- , on $\begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ you have $H = \begin{pmatrix} q \\ p \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ -p' \end{pmatrix} = q^t p' + p^t q'$

symmetric nondeg bilinear form and $A = \begin{pmatrix} q \\ p \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix} = -q^t p' + p^t q'$ antisymmetric bilinear form. Then

$$X = A^{-1}H = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \text{ seems to}$$

be the ~~main~~ ^{main} natural ~~operator~~ operator around which can be obtained from the data provided.

~~Notice~~ Notice that off diagonal I 's are the canonical isos $q^t p'$ from V_- to V_+



Next suppose V_+ equipped with extra structure like a symmetric bilinear form.

K''' At the moment you have reviewed the hyperbolic space construction $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ where $V_- = V_+^*$, the isom. $\text{canon } V_+ \xrightarrow{\sim} V_-^*$ given by $p^t q$
 $V_- \xrightarrow{\sim} V_+^*$ ——— $q^t p$

The canonical symmetric bilinear form and anti-sym.

$$A = \begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix}$$

$$H = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix}$$

$$X = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \quad X = \varepsilon !!!$$

~~Next~~ Next. You want very much to handle an ungraded harmonic oscillator, i.e. a vector space W equipped with a pos. def. symm. form $H: W \rightarrow W^*$ and an anti-symm. nondeg form $A: W \rightarrow W^*$

The tool to use you hope, is the ~~hyperbolic~~ hyperbolic space

$$\begin{pmatrix} V_+ \\ V_- \end{pmatrix} = \begin{pmatrix} W \\ W^* \end{pmatrix}$$



Maps you have

$$\begin{pmatrix} W \\ W^* \end{pmatrix} \longleftarrow \begin{pmatrix} W \\ W^* \end{pmatrix}$$

Start ^{again} with W a real v.s. equipped with $H: W \rightarrow W^*$ pos. def. symm. and $A: W \rightarrow W^*$ nondeg antisymm. $X = A^{-1}H$ skewsymm. operator on W , first H . Q: What

consequences of this structure: A, H, X on W are there for the hyperbolic space $V = \begin{pmatrix} W \\ W^* \end{pmatrix}$? Idea: Infinitesimal symplectic transf on V are in 1-1 corresp with symmetric ~~forms~~ forms. by the graph construction. Thus given $B: W \rightarrow W^*$ any bilinear form, one gets a subspace $\Gamma_B = \begin{pmatrix} 1 \\ B \end{pmatrix} W$ of V . It should be true that Γ_B is Lagrangian $\iff B = B^t$.

$$\begin{pmatrix} 1 \\ B \end{pmatrix} q = \begin{pmatrix} q \\ Bq \end{pmatrix} \quad \begin{pmatrix} q \\ Bq \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ Bq' \end{pmatrix} = -q^t Bq' + \underbrace{(Bq)^t q'}_{q^t B^t q'}$$

$$is = 0 \quad \forall q, q' \Leftrightarrow -B + B^t = 0. \quad \text{Yes.}$$

Also you have $\begin{pmatrix} C \\ 1 \end{pmatrix} W^*$ is Lagrangian ($C: W^* \rightarrow W$)

when? $\begin{pmatrix} C \\ 1 \end{pmatrix} p = \begin{pmatrix} Cp \\ p \end{pmatrix} \quad 0 = \begin{pmatrix} Cp \\ p \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} Cp' \\ p' \end{pmatrix} = -p^t C^t p' + p^t C p'$

$$\forall p, p' \Leftrightarrow -C^t + C = 0. \quad \text{I guess you might like complementary Lagrangian subspaces: } \Gamma_B \oplus \Gamma_C = V.$$

$$\begin{pmatrix} 1 \\ B \end{pmatrix} W \oplus \begin{pmatrix} C \\ 1 \end{pmatrix} W^* \xrightarrow[?]{\sim} \begin{pmatrix} W \\ W^* \end{pmatrix}$$



Let's try a different approach
Start with V equipped with H pos def symm
 A ~~non~~ nondeg anti-symm.

Then you get $X = A^{-1}H$ skew symm nondeg op on V .
Then form $X = |X|J$ where $J^2 = -1$.

Consider V complex with H pos def herm. bil.

IDEA you've forgotten that for a ~~complex~~ complex vector space V equipped with hermitian inner product, then the real part of this product (v, v') is a pos. def symmetric bilinear form and the imaginary part is a symplectic form. I think it's true that this oscillator has ^{as a single} frequency = 1.

Unfinished: Relation between an ungraded harmonic oscillator W and the hyperbolic space $\begin{pmatrix} W \\ W^* \end{pmatrix} = V$. The idea might be clearer in the case of quadratic forms, where you ~~have~~ have the **Witt group** defined by orthogonal direct sum with hyperbolic spaces set = 0.

μ''' Let's return to LC networks with external modes. ~~Recall that at some point you obtained a kind of response function from a subquotient of a polarized Euclidean space~~

~~Recall that at some point you obtained a kind of response function from a subquotient of a polarized Euclidean space~~

Classical response from a harmonic oscillator.

Review the mechanical oscillator:

Phase space $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \cong \begin{pmatrix} q \\ p \end{pmatrix}$ where $V_- \cong V_+^*$
and $V_+ \xrightarrow{\sim} V_-^*$, $q \mapsto (p \mapsto p^t q)$ $p \mapsto (q \mapsto q^t p)$

Symplectic form $A: \begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix}$

where the 1 has to be interpreted via duality pairing

Symm. form $H: \begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix}$

Symplectic flow $X = A^{-1}H = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} k & 0 \\ 0 & m^{-1} \end{pmatrix} = \begin{pmatrix} 0 & m^{-1} \\ -k & 0 \end{pmatrix}$

i.e. $\dot{q} = m^{-1}p$, $\dot{p} = -kq$. ~~Substituting~~

~~Next change coordinates~~ Next change variables.

You assume H pos. def., choose orth bases in V_+, V_- so k, m^{-1} become diagonal \mathbf{I} . Let $q = gQ, p = hP$

where $q^t k q = Q^t (g^t k g) Q = Q^t Q$

$p^t m^{-1} p = P^t (h^t m^{-1} h) P = P^t P$

duality pairing $q^t p = Q^t g^t h P$ $p^t q = P^t h^t g Q$

$A = \begin{bmatrix} g & 0 \\ 0 & h \end{bmatrix} \begin{pmatrix} Q \\ P \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{bmatrix} g & 0 \\ 0 & h \end{bmatrix} \begin{pmatrix} Q' \\ P' \end{pmatrix}$

$\begin{pmatrix} g^t & 0 \\ 0 & h^t \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} g & 0 \\ 0 & h \end{pmatrix} = \begin{pmatrix} 0 & -g^t h \\ h^t g & 0 \end{pmatrix}$

v'''

~~$$A = \begin{pmatrix} Q \\ P \end{pmatrix}^t \begin{pmatrix} 0 & -I \\ I & 0 \end{pmatrix} \begin{pmatrix} Q' \\ P' \end{pmatrix}$$~~

Repeat: $g = gQ, p = hP \quad g^t k g = Q^t (g^t k g) Q$

$p^t m^{-1} p = P^t \underbrace{h^t m^{-1} h}_I P$, Then $\overset{t}{g} P = Q^t g^t h P$

$$A = \begin{pmatrix} g \\ p \end{pmatrix}^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} g' \\ p' \end{pmatrix}$$

$$= \begin{pmatrix} Q \\ P \end{pmatrix}^t \begin{pmatrix} g^t & 0 \\ 0 & h^t \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} g & 0 \\ 0 & h \end{pmatrix} \begin{pmatrix} Q' \\ P' \end{pmatrix}$$

$$\begin{pmatrix} 0 & -g^t h \\ h^t g & 0 \end{pmatrix}$$

$$X = A^{-1} H = \begin{pmatrix} 0 & (h^t g)^{-1} \\ -(g^t h)^{-1} & 0 \end{pmatrix} = \begin{pmatrix} 0 & -T^* \\ T & 0 \end{pmatrix} \quad \text{where } T = -(g^t h)^{-1}$$

~~$Q = g^{-1} q, P = h^{-1} p \quad k = (g^t)^{-1} g^t = (g^{-1})^t g^{-1}$~~

~~$Q^t Q = g^t (g^{-1})^t g^t g = g^t g = g^t k g$~~

~~$k = g^t g, m^{-1} = h^t h, g^t k g = (g^t g) (g g^t) = Q^t Q$~~

~~$p^t g = P^t (h/g) Q = P^t (g/h^t) Q$~~

$H = \frac{1}{2} q^2 + \frac{1}{2} p^2$

$\dot{q} = \frac{\partial H}{\partial p} = p, \quad \dot{p} = -\frac{\partial H}{\partial q} = -q$

$X = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$

~~Discuss an LC network, closed, & connected~~
where closed means no "external" nodes.

~~Response to an applied force on a~~
harmonic oscillator seems to ^{be} a quadratic form depending on s - it seems non dynamic. e.g.

$$m\ddot{x} + \epsilon\dot{x} + kx = f(t) = A e^{st} \text{ yields } x = B e^{st} \text{ where}$$

$$B = \frac{A}{m\omega^2 + \epsilon\omega + k}. \text{ Steady-state as opposed to transient}$$

Program: You have this ^{image} picture of ~~a~~ a closed connected LC network given by an orthogonal repn of F, ϵ . You want ~~the~~ the analog for a conn. LC network with external nodes, which you might call an open LC network. Hopefully the external variables, i.e. the ~~external~~ external state space, supports a response function which is a quadratic form depending on s .

~~Now list possible lines of inquiry:~~
Now list possible lines of inquiry:

(1) Terminology open + closed networks suggests there is ~~a~~ a cobordism analogy. Also cobordism involves quadratic forms. Harmonic oscillators involve both A, H bilinear forms.

(2) Consider a connected LC network ^{equipped} with an input node and ground nodes. You have some ideas about attaching a voltage source to these nodes. ~~For instance, how~~ For instance, how the external node changes ~~the~~ the Kirchhoff constraints. You should study this situation using the polarized Euclidean space version of a closed LC network. One problem ~~might~~ might be that the dominant obs (V_c, I_L) have ~~to be~~ to be ~~related~~ related to the applied voltage V_a . Maybe all you have to do

is to project V_a onto the space of dominant vblo, better: to express V_a in terms of (V_c, I_L) , then use this as a forcing term for the oscillator.

Is there a K-theory aspect to quadratic forms?

Answer should be yes, because there's a Witt group generated by iso classes of quadratic spaces, with relations saying that the Witt class respects direct sums and that hyperbolic quadratic spaces have Witt inv = 0.

Ex. Work over a field K containing $\frac{1}{2}$. You want to take any quadratic space and show it's a summand of a hyperbolic space. The latter have the form $V = \begin{pmatrix} W \\ W^* \end{pmatrix}$ with quad form $\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q & 0 \\ 0 & p \end{pmatrix} = q^t p + p^t q$.

Consider $W=K$ with quadratic form qag where $a \in K$ is nonzero. Is it possible to find $b \in K$ such that $\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} a & 0 \\ 0 & b \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$ is hyperbolic. $b = -a$ should work.

The quad form when $b = -a$ is $a(q^2 - p^2) = a(q+p)(q-p)$.
 $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} q-p \\ q+p \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$? Diagonalize $\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$

Pick a vector with norm $\neq 0$ $v_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$. Find c s.t.
 $v_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} + c \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} c \\ 1 \end{pmatrix}$ $\begin{pmatrix} c \\ 1 \end{pmatrix}^t \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = c$?

Start again $\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix} = q^2 - p^2$. Now put $e_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $e_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \begin{pmatrix} c \\ 0 \end{pmatrix} = \begin{pmatrix} c \\ 1 \end{pmatrix}$

$$e_1 \cdot e_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}^t \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 1 \quad e_1 \cdot e_2 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}^t \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} c \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}^t \begin{pmatrix} c & 0 \\ 0 & -1 \end{pmatrix} = c$$

$$e_2 \cdot e_2 = \begin{pmatrix} c \\ 1 \end{pmatrix}^t \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} c \\ 1 \end{pmatrix} = c^2 - 1. \quad \text{get } \begin{pmatrix} 1 & c \\ c & c^2 - 1 \end{pmatrix} \quad \text{note det} = c^2 - 1 - c^2 = -1 = (1)(-1). \checkmark$$

What does this mean? You are trying to show that the quad form $\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ is hyperbolic.

$\Pi''' \quad \begin{pmatrix} q & 0 \\ p & 0 \end{pmatrix}^t \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix} = q^2 - p^2$ is hyperbolic means

$\left[\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in GL(2) \text{ s.t. } \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a-c & a-b \\ b-d & c-d \end{pmatrix} \right]$

$= \begin{pmatrix} a^2-c^2 & ab-cd \\ ba-dc & b^2-d^2 \end{pmatrix} \stackrel{?}{=} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

$\det = -(ad-bc)^2$

$(qb)^2 - (ad)^2 - (bc)^2 + (cd)^2$
 $(qb)^2 + 2abcd + (cd)^2 - (\cancel{ad-bc})^2$
 $ad-bc$

$a=1, c=+1, b=+1, d=-1$

$\begin{pmatrix} 1 - (+1)^2 & (-1) - (+1) \end{pmatrix}$



$a=b=c=1, d=-1$
 $ab-cd = 1+1$

$\begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}^t \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & +1 \end{pmatrix}$

$= \begin{pmatrix} 0 & +2 \\ +2 & 0 \end{pmatrix} ?$

$\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ -1 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -2 \\ -2 & 0 \end{pmatrix}$

So now you ~~know~~ should know that on $\begin{pmatrix} W \\ W^* \end{pmatrix}$ for $\begin{pmatrix} s & \\ & -s^{-1} \end{pmatrix}$ is hyperbolic. ?

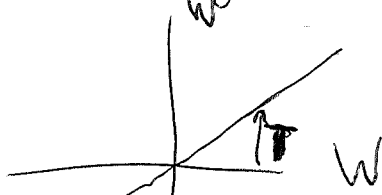
Next. Suppose given $S: W \xrightarrow{\sim} W^*$ symm.

Here ~~is~~ should be the idea. Given W form

$\begin{pmatrix} W \\ W^* \end{pmatrix}$ with $\begin{pmatrix} q & 0 \\ p & 0 \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix}$

\mathfrak{g}'' Point: A maximal isotropic subspace should yield a hyperbolic form.

Consider an



$$\Gamma = \begin{pmatrix} 1 \\ T \end{pmatrix} W \quad \text{a complement to } W^*$$

Γ isotropic

$$\Leftrightarrow T + T^* = 0$$

you want to recall the skew-symmetric operators = Lie algebra.

$$\left(\begin{pmatrix} 1 \\ T \end{pmatrix} W \right)^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ T \end{pmatrix} W^{-1} = 0$$

$$W^t \begin{pmatrix} 1 & T^* \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ T \end{pmatrix} W^{-1}$$

$$\searrow W(T + T^*)W^{-1}$$

The question bothering you is whether a non-deg quadratic space $W \xrightarrow{S} W^*$ can be embedded in

the hyperbolic space $V = \begin{pmatrix} W \\ W^* \end{pmatrix}$ equipped w $\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix}$

So you want a ~~set~~ ^{isometric} graph $\begin{pmatrix} 1 \\ S \end{pmatrix} : W \rightarrow V$. ~~that~~

For this to be an embedding you ~~are~~ need



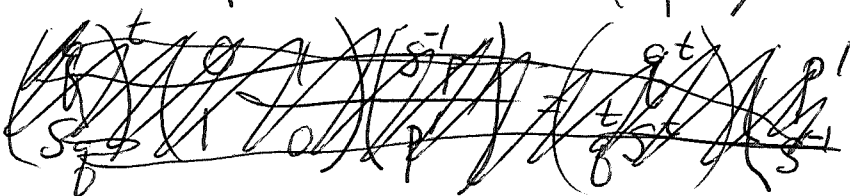
$$\begin{pmatrix} q \\ S q \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q' \\ S q' \end{pmatrix} = q^t S q' + q^t S^t q'$$

so up to 2^{-1} it's clear.

Does \exists a complement?

$$\begin{pmatrix} S^{-1} \\ 1 \end{pmatrix} W^*$$

$$\begin{pmatrix} S^{-1} p \\ p \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} S^{-1} p' \\ p' \end{pmatrix} = p^t (S^{-1})^t p' + p^t S^{-1} p'$$



σ''' Repeat, W quad space: $W \xrightarrow[S]{S} W^*$ $S = S^t$.

Form $V = \begin{pmatrix} W \\ W^* \end{pmatrix}$ quad form $\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q \\ p \end{pmatrix} = q^t p + p^t q$

Embeddings ~~$\begin{pmatrix} q \\ p \end{pmatrix} \mapsto \begin{pmatrix} q \\ p \end{pmatrix}$~~
 $q \mapsto \begin{pmatrix} q \\ S q \end{pmatrix}$, $p \mapsto \begin{pmatrix} S^{-1} p \\ p \end{pmatrix}$
 $W \hookrightarrow V$ $W^* \hookrightarrow V$

Check first that $q \mapsto \begin{pmatrix} q \\ S q \end{pmatrix}$ ~~respect~~ respect quad form

$$\begin{pmatrix} q \\ S q \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q \\ S q \end{pmatrix} = \begin{pmatrix} q^t & q^t S^t \end{pmatrix} \begin{pmatrix} S q \\ q \end{pmatrix} = q^t S q + q^t S^t q = 2 q^t S q$$

Next ~~compute~~ compute orth space.

$$\begin{pmatrix} q' \\ p' \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q \\ S q \end{pmatrix} = q'^t S q + p'^t q = 0 \quad \forall q$$

$$\Rightarrow q'^t S + p'^t = 0$$

$$\Rightarrow (S q')^t + p'^t = 0$$

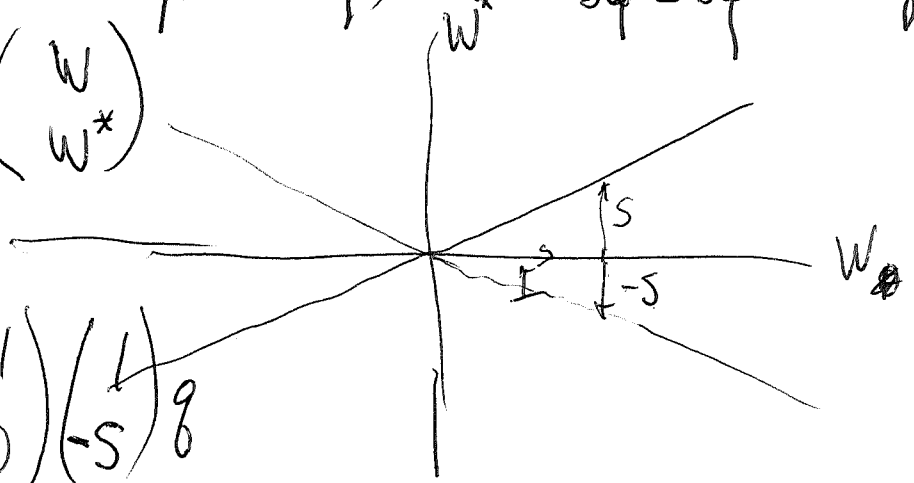
$\therefore p' = -S q'$

So it seems that in V the subspaces $\begin{pmatrix} 1 \\ S \end{pmatrix} W_+$ and ~~$\begin{pmatrix} 1 \\ S \end{pmatrix} W_+$~~

$\begin{pmatrix} 1 \\ -S \end{pmatrix} W_+$ are orthogonal $\begin{pmatrix} 1 \\ -S \end{pmatrix}^t \begin{pmatrix} S \\ 1 \end{pmatrix} = (1 - S^t) \begin{pmatrix} S \\ 1 \end{pmatrix} = S - S^t$

complementary because $\begin{pmatrix} q \\ -S q \end{pmatrix} = \begin{pmatrix} q' \\ S q' \end{pmatrix} \Rightarrow q' = q$
 $-S q = S q' \Rightarrow S q = 0$

Next ~~check~~
 $\begin{pmatrix} 1 \\ S \end{pmatrix} W \subset \begin{pmatrix} W \\ W^* \end{pmatrix}$



$$q^t (1 - S^t) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ -S \end{pmatrix} q$$

$$q^t (1 - S^t) \begin{pmatrix} -S q \\ q \end{pmatrix} = q^t (-S q - S^t q) = -2 q^t S q$$

III ~~Begin~~ Begin with $S: W \rightarrow W^*$ S symmetric

Form $V = \begin{pmatrix} W \\ W^* \end{pmatrix}$ with $\begin{pmatrix} q \\ p \end{pmatrix}^t \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} q' \\ p' \end{pmatrix} = q^t p' + p^t q'$

Look at ~~W~~ $W \xrightarrow{\begin{pmatrix} 1 \\ s \end{pmatrix}} \begin{pmatrix} W \\ W^* \end{pmatrix} \begin{pmatrix} 1 & 0 \\ s & 1 \end{pmatrix}^t \begin{pmatrix} 1 \\ s \end{pmatrix} q = q^t (1 \ s^t) \begin{pmatrix} 1 \\ s \end{pmatrix} q = q^t (s + s^t) q$

$\begin{pmatrix} 1 \\ s \end{pmatrix} q^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ -s \end{pmatrix} q' = q^t (1 \ s^t) \begin{pmatrix} -s \\ 1 \end{pmatrix} q' = q^t (-s + s^t) q$

Next take $A: W \rightarrow W^*$ antisym $\begin{matrix} -2A \\ " \\ -A + A^t \end{matrix}$

$\begin{pmatrix} 1 \\ A \end{pmatrix} q^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ A \end{pmatrix} q = q^t (1 \ A^t) \begin{pmatrix} -A \\ 1 \end{pmatrix} q = q^t (A - A^t) q$

$\begin{pmatrix} 1 \\ -A \end{pmatrix} q^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ -A \end{pmatrix} q = q^t (A - A^t) q$

$\begin{pmatrix} 1 \\ -A \end{pmatrix} q^t \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ A \end{pmatrix} q = q^t (1 \ -A^t) \begin{pmatrix} -A \\ 1 \end{pmatrix} q = q^t (-A - A^t) q$

$q^t (1 \ s^t) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ s \end{pmatrix} q' = q^t (1 \ s^t) \begin{pmatrix} s \\ 1 \end{pmatrix} q = q^t (s + s^t) q'$

$q^t (1 \ s^t) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ -s \end{pmatrix} q' = q^t (-s + s^t) q' = 0$

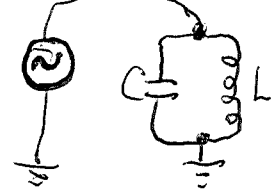
$q^t (1 \ -s^t) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ -s \end{pmatrix} q' = q^t (1 \ -s^t) \begin{pmatrix} -s \\ 1 \end{pmatrix} q = q^t (-s - s^t) q'$

IDEA: When you look at

~~response~~ quantum response of the harmonic oscillator it might be useful to mix A and S in some fashion. For instance the pencil $A + zS$.

For the moment you need to treat ~~the~~ the harmonic oscillator with ~~external~~ V_{ext} at an external mode.

U'''
 $v \quad l \quad e$
 $2 - 1 + 2 = 3$



dominant obls. V_C, I_L

$V_{ap} = V_C = V_L$

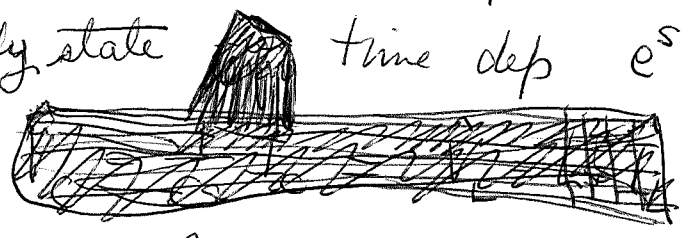
$C \partial_t V_C = I_C$

$I_{ap} = I_C + I_L$

$L \partial_t I_L = V_L$

steady state

time dep e^{st}

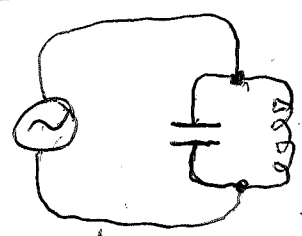


$C s \hat{V}_C = \hat{I}_C$
 $L s \hat{I}_L = \hat{V}_L$

$C s \hat{V}_{ap} = \hat{I}_C$
 $\frac{1}{L s} \hat{V}_{ap} = \hat{I}_L$

$(C s + \frac{1}{L s}) \hat{V}_{ap} = \hat{I}_C + \hat{I}_L = \hat{I}_{ap} \quad \therefore \frac{\hat{V}_{ap}}{\hat{I}_{ap}} = \frac{1}{C s + \frac{1}{L s}}$

STUPID IDEA: ~~scribble~~ Non uniqueness of decomposition of a p-torsion R-module, R PID, e.g. Jordan normal forms, could this lead to an interesting random field?

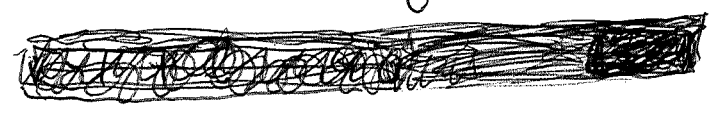


$v \quad l \quad e$
 $2 - 1 + 2 = 3$

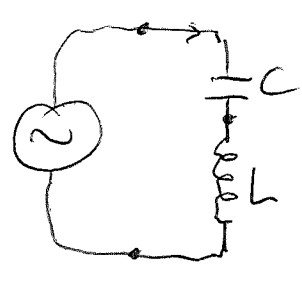


Questions: What are the solutions for this network? You want time dependent solns.

You expect there to be ~~scribble~~ a kind of steady state solution caused by $V_{ap}(t)$ - assume $V_{ap} = 0$ for $t \ll 0$ - with a transient solution ^{super}imposed. The general solution should be a particular solution + the general solution of the homogeneous eqn.



$v \quad l \quad e$
 $3 - 1 \quad 1 \quad 3$




$V_{ap} = V_C + V_L$
 $\frac{\hat{V}_{ab}}{\hat{I}_{ab}} = \frac{\hat{V}_C}{\hat{I}_C} + \frac{\hat{V}_L}{\hat{I}_L} = \frac{1}{C s} + L s$

φ'' So how are you going to handle an applied voltage source between two nodes. It seems that you need to add an edge to the graph.

The problem ~~then~~ is how to treat this new edge. ~~What happens from~~

the polarized Euclidean viewpoint. $W \subset \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \rightarrow W^\perp$
 W is the space of node ~~potentials~~ potentials, functions on the nodes mod constants. The external pair of nodes gives a linear form on W .

Idea: Use what you've learned about embedding a quadratic space into a hyperbolic one. ~~the space~~

Consider  as this moves in time you get ~~an edge~~ a varying voltage. In general ~~you have~~ for each linear functional on W you

Focus upon the ~~idea~~ cobordism idea

Observation: When you form ~~the~~ the spaces of cochains + chains you are forming hyperbolic quadratic spaces:

$$\bar{C}^0 \hookrightarrow C^1 \twoheadrightarrow H^1$$

$$\bar{C}_0 \leftarrow C_1 \twoheadleftarrow H_1$$

$$\begin{pmatrix} V \\ V^* \end{pmatrix} \begin{pmatrix} 0 \\ p \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 \\ p' \end{pmatrix}$$

(symmetric bilinear)

You really have the "power" quadratic form. So what about the pos def. ~~quadratic form~~ quadratic form related to the dynamics? Answer:

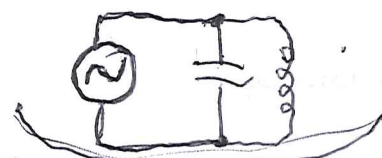
$$C^1 \xrightarrow{S} C_1$$

C, S is embedded in the original quadratic space via $\Gamma_S = \begin{pmatrix} 1 \\ S \end{pmatrix} C^1$ with the orthogonal complement Γ_{-S} .

The original quadratic space
the hyperbolic quadratic space
orthogonal complement Γ_{-S} .

χ''

voltage source source to the



By attaching the two nodes, you are

weakening the Kirchhoff constraints! Ideas to pursue: cobordism in the context of quadratic forms. Let's begin with the closed connected

$$\chi'' = 2 - 1 + 1 = 2.$$

LC network: State space is 4 dim (without Kirchhoff constraints; call this the edge state space.



~~State space is 4 dim (without Kirchhoff constraints; call this the edge state space.~~

You need to link your understanding of a closed LC network (conn.) to a voltage source applied between external nodes. Why does this seem difficult? (i) the graph acquires an extra edge which seems to have ^{for the applied voltage source} its own voltage + current states making a 2-dimensional phase space, (ii) you want to treat the applied voltage as a forcing term, the possible forcing terms correspond to dominant edges,

Start again, need review of something, maybe list ideas, • cobordism idea: Think of a graph with external nodes as a singular 1-manifold with boundary.

Review the ~~constraint~~ situation for a closed connected LC network. You have a phase space, or state space consisting of the voltage drop and current for each edge. A state is given by coordinates $(V, I) \in \mathbb{C}^1 \times \mathbb{C}^1$; its power is $V \cdot I$, ~~between~~ the duality pairing between 1-cochain and 1-chains.

ψ''' In order to describe the motion by a first order DE you need to introduce phase spaces. This is not correct. Things are strange because the dynamics on the edges are like motion of a particle with constant velocity. The point is that only after restricting to Kirchhoff states do you get a flow.

Here's ~~what needs to be understood~~ what needs to be understood:

To obtain the motion of the ~~closed~~ closed LC circuit you solve the I.V.P. using the dominant variables (V_C, I_L) , which are system of coords on the Kirchhoff space. This means working in the hyperbolic space $C^1 \times C_1$.

~~But to understand~~ But to understand what's happening you ~~calculate~~ calculate the flow in $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ which is C^1 equipped with the power quadratic form + polarization.

Program: ~~To understand better the~~ "mechanical" harmonic oscillator:

$$\begin{pmatrix} S & T^* \\ -T & S \end{pmatrix} \begin{pmatrix} \hat{q} \\ \hat{p} \end{pmatrix} = \begin{pmatrix} q(0) \\ p(0) \end{pmatrix}$$

arising from an LC network which is suitably nondegenerate. The C^1 puzzle: You start with a polarized Euclidean space A , then construct ~~the~~ the "phase space" $\begin{pmatrix} C^1 \\ C_1 \end{pmatrix}$ which has 4 components $\begin{pmatrix} V_C & V_L \\ I_C & I_L \end{pmatrix}$, symplectic structure. There should be in all of this a symplectic quotient yielding a mechanical harmonic oscillator.

ω''' Make attempt to understand constraints.

Would it help to look at a resistance network?

$$\bar{C}^0 \leftrightarrow C^1 \longrightarrow H^1$$

$$\downarrow R^{-1}$$

$$\bar{C}_0 \longleftarrow C_1 \longleftarrow H_1$$

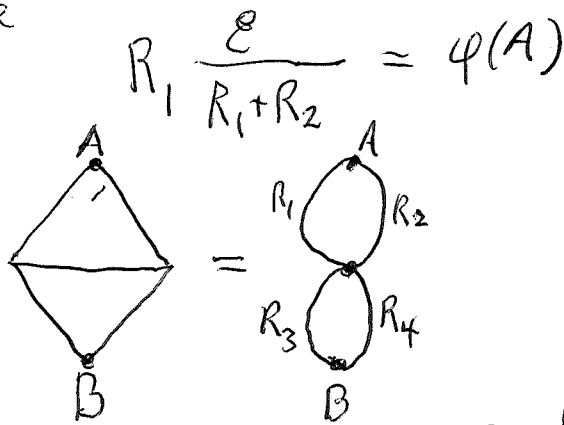
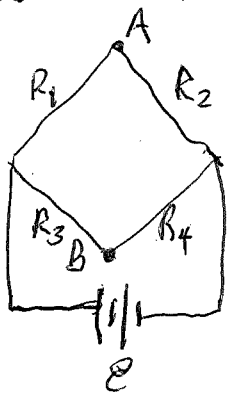
What ~~are~~ are the natural questions?

- R^{-1} yields a pos. def inner product on C^1 : the power dissipated in a given edge voltage configuration

This positive definite form on C^1 induces one on \bar{C}_0 , the space of node potentials, and ^{one on} H_1 . ~~It~~ It seems that the pos. def form on H_1 is more natural as a pos. def. form on H_1 , the space of loop currents.

You are looking at Hodge theory ~~for~~ for a graph. The only result you can see is the orthogonal decomposition. There are "harmonic" ~~1-cochains~~ 1-cochains and 1-chains

Thevenin example



$$R_1 \frac{E}{R_1 + R_2} = \varphi(A) \quad R_3 \frac{E}{R_3 + R_4} = \varphi(B)$$

$$E_0 = \varphi(A) - \varphi(B) = \left(\frac{R_1}{R_1 + R_2} - \frac{R_3}{R_3 + R_4} \right) E$$

$$R_0 = \frac{R_1 R_2}{R_1 + R_2} + \frac{R_3 R_4}{R_3 + R_4}$$

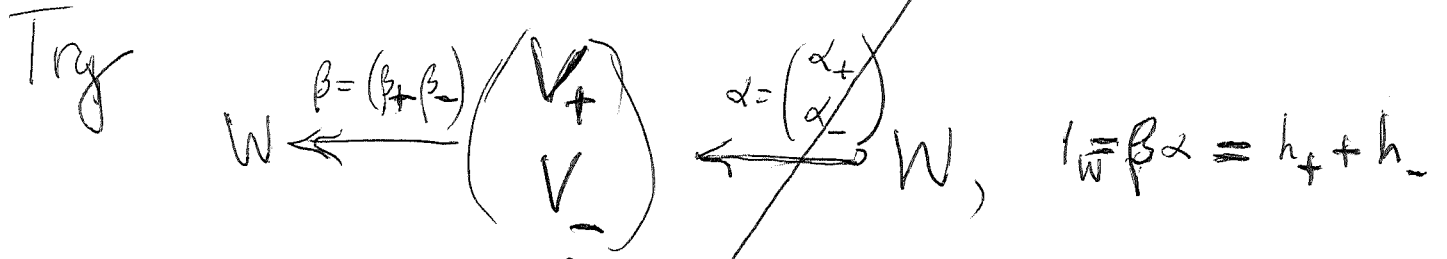
E_0, R_0 are the e.m.f. and internal resistance of the 1-port with ~~nodes~~ nodes A, B.

9" You've reviewed different pictures of a vector space equipped with 2 splittings: 0) repr of $\mathbb{Z}/2 \times \mathbb{Z}/2$

- 1) short exact sequence with splitting $\mathbb{Z}/2 \times \mathbb{Z}$
- 2) homotopy equivalence between length 1 complexes

Let's now restrict to f.dim. - you want the spectral theory understood clearly. ~~That's the case~~
 Begin with classifying irreducibles.

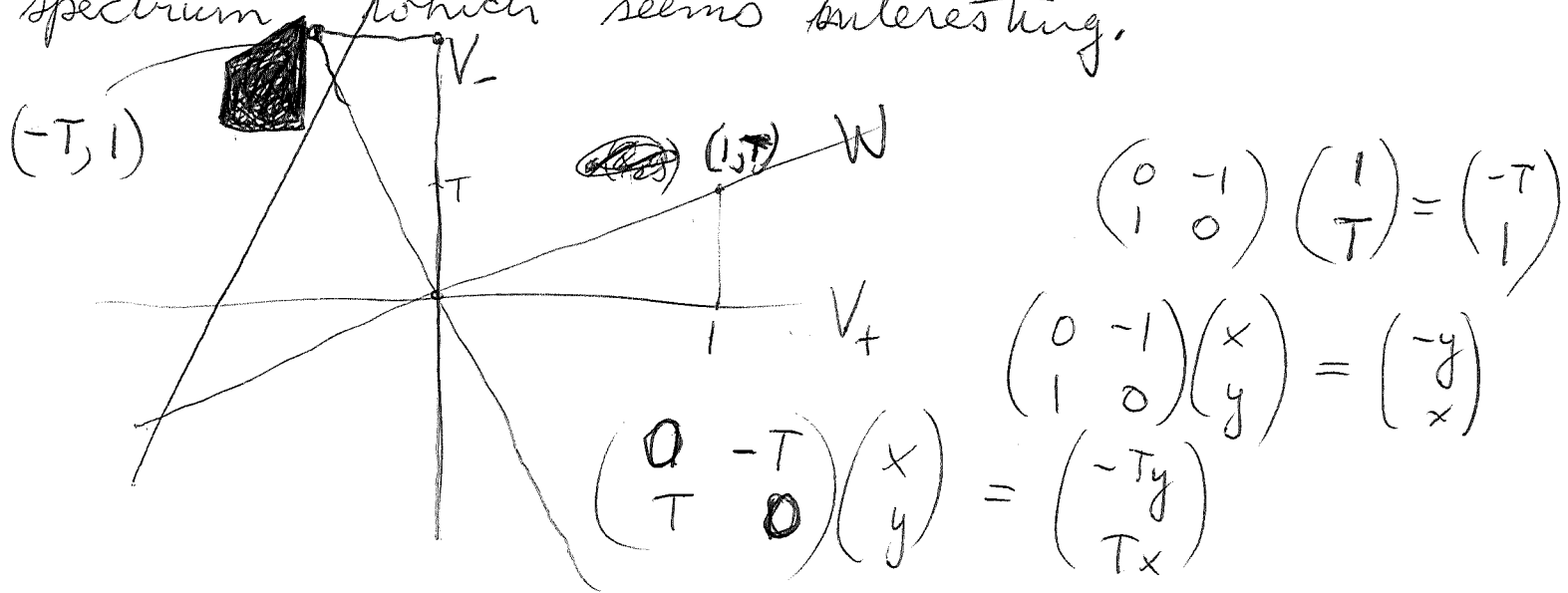
$$g = F\varepsilon \quad \frac{g+g^{-1}}{2} = \cos \theta \quad \text{if } g = e^{i\theta}$$



W should be the ~~the~~ $F = +1$ eigenspace.

$$p = \alpha\beta \quad p^2 = p \quad p = \frac{F+1}{2}$$

It's probably misleading to look first at the linear retract ~~retract~~ of a polarized vector space, because this situation suppresses part of the spectrum which seems interesting.



b" So you consider this V finite diml
 repr of $\langle F, \varepsilon \rangle$. Let $g v_0 = z v_0 \quad z \in \mathbb{C}^*$

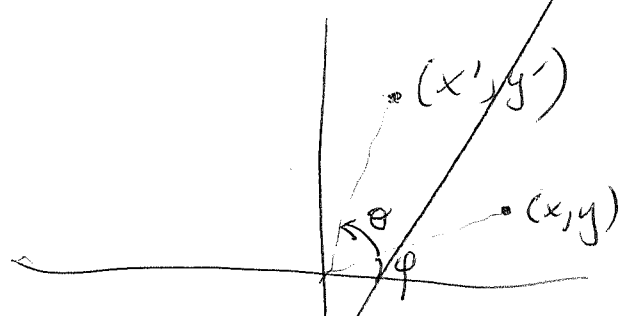
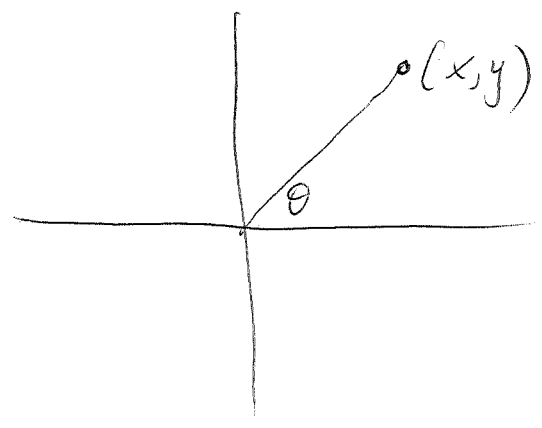
Then $g \varepsilon v_0 = z g^{-1} v_0 = z^{-1} \varepsilon v_0$
 $\varepsilon (a v_0 + b \varepsilon v_0) = b v_0 + a \varepsilon v_0$
 $g (a v_0 + b \varepsilon v_0) = a z v_0 + b z^{-1} \varepsilon v_0$

$\therefore g \mapsto \begin{pmatrix} z & 0 \\ 0 & z^{-1} \end{pmatrix} \quad \varepsilon \mapsto \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

$F = g \varepsilon \mapsto \begin{pmatrix} 0 & z \\ z^{-1} & 0 \end{pmatrix}$

Something is wrong with this representation
 because ~~the representation is not real~~ the
 good representation should be defined over \mathbb{R} .
 All the irreducible fin. diml. representations
 should be characters or 2 diml real reprs.

$$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$



$$(x', y') = r (\cos(\theta + \phi) + i \sin(\theta + \phi))$$

$$x' + iy' = e^{i\theta} (x + iy) = (\cos \theta + i \sin \theta) (x + iy)$$

$$= ((\cos \theta)x - (\sin \theta)y) + i((\sin \theta)x + (\cos \theta)y)$$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

C^n \mathbb{R}^2 f.d reps of $\langle F, \epsilon \rangle$

$$g = F\epsilon \mapsto \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}, \quad \epsilon \mapsto \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$F \mapsto g\epsilon = \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix}$$

~~$$\begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} \cos^2 \theta & \sin^2 \theta \\ 2 \sin \theta \cos \theta & \cos^2 \theta \end{pmatrix} = \begin{pmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & \cos 2\theta \end{pmatrix}$$~~

$$\frac{F+1}{2} = \frac{1}{2} \begin{pmatrix} 1+\cos \theta & \sin \theta \\ \sin \theta & 1-\cos \theta \end{pmatrix} = \begin{pmatrix} \cos^2(\frac{\theta}{2}) & \sin(\frac{\theta}{2}) \cos(\frac{\theta}{2}) \\ \sin(\frac{\theta}{2}) \cos(\frac{\theta}{2}) & \sin^2(\frac{\theta}{2}) \end{pmatrix}$$

$$1 + \cos 2\alpha = \cos^2 \alpha - \sin^2 \alpha + \cos^2 \alpha + \sin^2 \alpha = 2 \cos^2 \alpha$$

so $\frac{F+1}{2}$ projects onto $\begin{pmatrix} \cos(\frac{\theta}{2}) \\ \sin(\frac{\theta}{2}) \end{pmatrix} \mathbb{R}$

~~$$\frac{1-F}{2} = \frac{1}{2} \begin{pmatrix} 1-\cos \theta & -\sin \theta \\ -\sin \theta & 1+\cos \theta \end{pmatrix} = \begin{pmatrix} \sin^2(\frac{\theta}{2}) & -\sin(\frac{\theta}{2}) \cos(\frac{\theta}{2}) \\ -\sin(\frac{\theta}{2}) \cos(\frac{\theta}{2}) & \cos^2(\frac{\theta}{2}) \end{pmatrix}$$~~

dihedral group $\langle F, \epsilon \rangle = \langle \epsilon \rangle \rtimes g$ $g = F\epsilon$
 represent on \mathbb{R}^2 by

$$g \mapsto \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \quad \epsilon \mapsto \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$F = g\epsilon = \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix} \quad \text{tr} = 0$$

$$\det = -1$$

~~$$\frac{F+1}{2} = \begin{pmatrix} \cos^2 \frac{\theta}{2} & \sin \frac{\theta}{2} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \cos \frac{\theta}{2} & \sin^2 \frac{\theta}{2} \end{pmatrix} = \begin{pmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{pmatrix} \begin{pmatrix} \cos \frac{\theta}{2} & \sin \frac{\theta}{2} \end{pmatrix}$$~~

$$\begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{\begin{pmatrix} a & b \\ c & d \end{pmatrix}} \begin{pmatrix} W \\ W^\perp \end{pmatrix} \xleftarrow{\begin{pmatrix} a^* & c^* \\ b^* & d^* \end{pmatrix}} \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{\begin{pmatrix} a & b \\ c & d \end{pmatrix}} \begin{pmatrix} W \\ W^\perp \end{pmatrix}$$

8 operators 8 relations. You are looking at a representation of the inf dihedral group $\langle \varepsilon, F \rangle$, a ^{orthogonal?} unitary representations. You want to decompose it into irreducibles. What's the center of the group alg?

$$\frac{F\varepsilon + \varepsilon F}{2} = \frac{g + g^{-1}}{2}$$

$$(F + \varepsilon)^2 = F\varepsilon + \varepsilon F + 2$$

$$(F - \varepsilon)^2 = 2 - F\varepsilon - \varepsilon F$$

What is the partition

$$1_W = a^*a + c^*c$$

$$a = \frac{1+\varepsilon}{2} \frac{1+F}{2}$$

$$a^*a = \frac{1+F}{2} \frac{1+\varepsilon}{2} \cancel{\frac{1+\varepsilon}{2}} \frac{1+F}{2}$$

$$c^*c = \frac{1+F}{2} \frac{1-\varepsilon}{2} \frac{1+F}{2}$$

You should be able to assume $\frac{F\varepsilon + \varepsilon F}{2} \in (-1, 1)$ is a scalar operator, and then deduce everything else.

$$g = F\varepsilon = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$$

$$g^{-1} = \varepsilon F = \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix}$$

So imagine a ^{f.d. real} vector space Z equipped with involutions F, ε such that $\frac{F\varepsilon + \varepsilon F}{2}$ is the scalar operator λ . This is absurd.

This is absurd: You are given two involutions F, ε on a f.d. complex v.s. say complex to begin.

e'' ~~Hilbert space, $F \in \text{two}$~~

~~E f.d. Euclidean space,~~
 $F + \varepsilon$ two orthogonal involutions (for
an involution F orthogonal means $F^* = F^{-1} = F$
i.e. F is symmetric.

$g = F\varepsilon$ orthogonal transf on E

one know E splits ~~orthogonally~~ orthogonally into 2 planes
stable under g , but why should they be
stable under ε .

Go back to complex Hilbert space H with 2
unitary involutions F, ε .

Better, prove the decomposition into 2dimal rotations for
a real orthogonal matrix. So take an orthog
matrix, look at its characteristic equation. Eigenvalues
should lie in S^1 .

To understand why an orthog transf splits
into 2dimal rotations.

E Euclidean space i.e. real v.s. + pos. def. ^{symmetric} form
 g orthog transf $g^* = g^{-1}$, where $g^* = \text{transpose}$

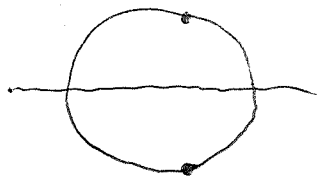
~~then~~ Complexify - ~~choose~~ ^{orth} an basis for E ,
then the orthog matrix g is unitary ~~in~~ in $M_n(\mathbb{C})$.

~~pick~~ Pick an eigenvector $g v = \lambda v \quad v \in \mathbb{C}^n$
 $g \bar{v} = \bar{\lambda} \bar{v}$

get 2 plane ~~basis~~ basis $\frac{v + \bar{v}}{2}, \frac{v - \bar{v}}{2i}$ Should get
2dimal rotation.

f'' What happens next? You started with a ~~set~~ Euclidean space + 2 orth inos F, ε .
 Put $g = F\varepsilon$ orth. ??
 Maybe go to the complex case first.

H ^{fd} Hilb F, ε unitary s.a. inv. $g = F\varepsilon$



because $\varepsilon g \varepsilon^{-1} = g^{-1}$ the spectrum of g is symmetric about real axis.

You can split H, F, ε into eigenspaces

for the s.a. operator $\frac{g+g^{-1}}{2} = \frac{F\varepsilon + \varepsilon F}{2}$

$$V_{\theta} = \{ \xi \in H \mid g\xi = e^{i\theta} \xi \}$$

$$V_{-\theta} = \{ \xi \in H \mid g\xi = e^{-i\theta} \xi \}$$

$$\varepsilon g \xi = \varepsilon e^{i\theta} \xi$$

$$g^{-1}(\varepsilon \xi) = e^{i\theta} (\varepsilon \xi)$$

$$\therefore \varepsilon(V_{\theta}) = V_{-\theta}, \quad \varepsilon(V_{-\theta}) = V_{\theta}$$

$$H = \begin{pmatrix} V_{\theta} \\ V_{-\theta} \end{pmatrix} \quad g \mapsto \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix} \quad \varepsilon \mapsto \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\frac{1}{2} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} e^{i\theta} & e^{i\theta} \\ e^{-i\theta} & e^{-i\theta} \end{pmatrix}$$

$$= \begin{pmatrix} \cos \theta & -i \sin \theta \\ -i \sin \theta & \cos \theta \end{pmatrix}$$

$$g'' \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} = \frac{1}{2} \begin{pmatrix} e^{i\theta} + e^{-i\theta} & i(e^{i\theta} - e^{-i\theta}) \\ \frac{e^{i\theta} - e^{-i\theta}}{i} & e^{i\theta} + e^{-i\theta} \end{pmatrix}$$

$$\frac{1}{2} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} \cos \theta & -i \sin \theta \\ -i \sin \theta & \cos \theta \end{pmatrix}$$

left mult. by $\begin{pmatrix} 1 & 0 \\ 0 & i \end{pmatrix}$ then right mult by $\begin{pmatrix} 1 & 0 \\ 0 & -i \end{pmatrix}$

$$\frac{1}{2} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix} \begin{pmatrix} 1 & +i \\ 1 & -i \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\cos \theta - e^{i\theta} = \frac{e^{i\theta} + e^{-i\theta}}{2} - e^{i\theta} = \frac{-e^{i\theta} + e^{-i\theta}}{2}$$

$$= -i \sin \theta$$

$$\begin{pmatrix} -i \sin \theta & -\sin \theta \\ \sin \theta & -i \sin \theta \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

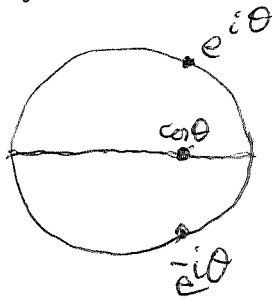
$$i \cos \theta + \sin \theta$$

$$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$$

$$\begin{matrix} e^{i\theta} & e^{-i\theta} \\ -ie^{i\theta} & +ie^{-i\theta} \end{matrix}$$

\mathbb{H}'' ~~Repeat~~ Repeat H fin. dim. Hilb
 with 2 unitary inv. F, ε . $g = F\varepsilon$ unitary
 since $g^{-1} = \varepsilon g \varepsilon^{-1}$ spectrum of g (which is a
 divisor supported on S^1) is symmetric about real axis.

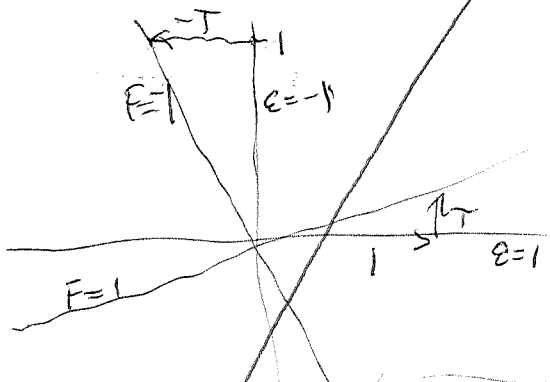
In fact ε sets up isom $V_\theta \xrightarrow{\sim} V_{-\theta}$ of



Decompose H according to the
 eigenvalues of $\frac{1}{2}(g+g^{-1}) = \frac{1}{2}(F\varepsilon + \varepsilon F)$.
~~Can~~ Can assume $\frac{1}{2}(g+g^{-1}) = \cos\theta$
 Id

Then $H = \begin{pmatrix} V_\theta \\ V_{-\theta} \end{pmatrix}$ $g \mapsto \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$ $\varepsilon \mapsto \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$.

You need to understand the real version, how
 it ~~arises~~ arises. Suppose given E f.d. Euclidean
 with 2 orth inv. F, ε . ~~Can~~ Can decompose
 E according to $\frac{1}{2}(g+g^{-1})$ which is symmetric
 ends ring of ~~an~~ an irreducible rep. $\mathbb{R}, \mathbb{C}, \mathbb{H}$?
 What you would like?



$$F \begin{pmatrix} 1 & -T \\ T & 1 \end{pmatrix} = \begin{pmatrix} 1 & -T \\ T & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$F(1+X) = (1+X)\varepsilon = \varepsilon(1-X)$$

$$\frac{1+X}{1-X} = F\varepsilon$$

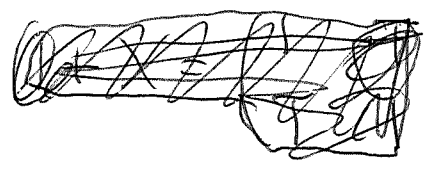
What's the puzzle? You're given E, F, ε
 such that $\frac{1}{2}(F\varepsilon + \varepsilon F)$ is λI , $-1 < \lambda < 1$. So
 there's a canonical form for F .

" Go back to $W \hookrightarrow \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \rightarrow W^\perp$

~~do have the same space~~ View this as the space $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ equipped with involution $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

and also with the involution F such that $F = +1$ on W , $F = -1$ on W^\perp . To simplify suppose $W = \begin{pmatrix} 1 \\ T \end{pmatrix} V_+$ where $T: V_+ \rightarrow V_-$.

The problem is to decompose ~~to rep~~ the dihedral representation given by (V, F, ε) into isotypical components. You believe that this should be ~~expressed in terms of~~ related to the characteristic values of the operator T , i.e. the eigenvalues of $(T^*T)^{1/2}$ and $(TT^*)^{1/2}$. Why?



Is there a phase quantity you're overlooking?

$\frac{1}{2}(F\varepsilon + \varepsilon F) = \frac{1}{2}(g + g^{-1})$ centralizes F, ε .

~~By the eigenvalue of~~ so the rep (V, F, ε) splits ~~into~~ into eigenspaces for $\frac{1}{2}(g + g^{-1})$: $(V_\lambda, F, \varepsilon)$

$1+X = \begin{pmatrix} 1 & -T^* \\ T & 1 \end{pmatrix}$

$F(1+X) = (1+X)\varepsilon = \varepsilon(1-X)$

$\frac{1}{2}(F\varepsilon + \varepsilon F) = \frac{1}{2} \begin{pmatrix} 1+X & \\ & 1-X \end{pmatrix}$

$\frac{1+X}{1-X} = F\varepsilon$

$\frac{1}{2} \frac{1+2X+X^2 + 1-2X+X^2}{1-X^2} = \frac{1+X^2}{1-X^2}$

f'' Repeat. $W \hookrightarrow \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \rightarrow W^\perp$. $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$

$\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ on V , $F = 1$ on W , -1 on W^\perp . Assume

$W = \begin{pmatrix} 1 \\ T \end{pmatrix} V_+$ where $T: V_+ \rightarrow V_-$. Then $W^\perp = \begin{pmatrix} -T^* \\ 1 \end{pmatrix} V_-$

$$F \begin{pmatrix} 1 & -T^* \\ T & 1 \end{pmatrix} = \begin{pmatrix} 1 & -T^* \\ T & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad \text{put } X = \begin{pmatrix} 0 & -T^* \\ T & 0 \end{pmatrix}$$

$$F(1+X) = (1+X)\varepsilon = \varepsilon(1-X) \Rightarrow \frac{1+X}{1-X} = F\varepsilon$$

You know $\frac{1}{2}(F\varepsilon + \varepsilon F) = \text{[scribble]} \frac{1}{2}(g+g^*)$ is hermitian and central, so that (V, F, ε) splits into eigenspaces $(V_\lambda, F_\lambda, \varepsilon)$ where $\frac{1}{2}(g+g^{-1}) = \lambda$ on V_λ .

You have $\frac{1}{2}(g+g^{-1}) = \frac{1}{2} \left(\frac{1+X}{1-X} + \frac{1-X}{1+X} \right) =$

$$\frac{1}{2} \left(\frac{1+2X+X^2+1-2X+X^2}{1-X^2} \right) = \frac{1+X^2}{1-X^2} \quad X^2 = \begin{pmatrix} -T^*T & 0 \\ 0 & -TT^* \end{pmatrix}$$

$$\frac{1+X^2}{1-X^2} = \begin{pmatrix} \frac{1-T^*T}{1+T^*T} & 0 \\ 0 & \frac{1-TT^*}{1+TT^*} \end{pmatrix} = \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}$$

$$\frac{1-\mu}{1+\mu} = \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix} \mu = \lambda \quad -1 \leq \lambda \leq 1$$

$$\mu = \begin{pmatrix} 1 & -1 \\ -1 & -1 \end{pmatrix} (\lambda) = \frac{-\lambda+1}{\lambda+1} = \frac{1-\lambda}{1+\lambda}$$

k^n V fd Hilb with F, ε $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$g = F\varepsilon$ is unitary, $\frac{1}{2}(g+g^{-1})$ is herm., let $\xi \in V$ be a unit vector which is an eigenvector for $\frac{1}{2}(g+g^{-1})$: $\frac{1}{2}(g\xi + g^{-1}\xi) = \lambda\xi$
 $-1 \leq \lambda \leq 1$. ~~Assume $\lambda \in (-1, 1)$. Let $T = \mathbb{C}g\xi + \mathbb{C}g^{-1}\xi$.~~

~~Claim T stable under F, ε because $F, \varepsilon, \frac{1}{2}(g+g^{-1})$ commute with,~~
 the λ -eigenspace₁ of $\frac{1}{2}(g+g^{-1})$ is stable under F, ε . Let $\xi \in V_+$
 be a unit eigenvector for g : $g\xi = e^{i\theta}\xi$. Then $g^{-1}\varepsilon\xi = e^{i\theta}\varepsilon\xi$
 $g(\varepsilon\xi) = e^{-i\theta}\varepsilon\xi$. $\begin{pmatrix} \mathbb{C}\xi \\ \mathbb{C}\varepsilon\xi \end{pmatrix} = \mathbb{C}\xi + \mathbb{C}\varepsilon\xi$ stable under ε, g with
 $g(a\xi + b\varepsilon\xi) = ae^{i\theta}\xi + be^{-i\theta}\varepsilon\xi$ $g \mapsto \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$ $\sigma \mapsto \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

V fd Hilb with $F, \varepsilon, g = F\varepsilon$ ~~unitary~~ $V = \bigoplus V_\theta$
 $\sigma V_\theta = V_{-\theta}$

$W \xrightarrow{\alpha} \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \rightarrow W^\perp$ s.h.o. case ~~show case~~
 $\alpha = \begin{pmatrix} \alpha_+ \\ \alpha_- \end{pmatrix}$ $\alpha^* \alpha = \begin{pmatrix} \alpha_+^* & \alpha_-^* \end{pmatrix} \begin{pmatrix} \alpha_+ \\ \alpha_- \end{pmatrix} = \overbrace{\alpha_+^* \alpha_+}^{h_+} + \overbrace{\alpha_-^* \alpha_-}^{h_-} = 1$
 h_+, h_- tell you how energy is distributed between C, L edges.

Example. $\bar{C}^0 \xrightarrow{\alpha} \begin{pmatrix} C \\ C \\ L \end{pmatrix} \rightarrow H^1$

$\alpha(V_0) = \begin{pmatrix} V_0 \\ V_0 \end{pmatrix}$ $\left\{ \begin{pmatrix} V_C \\ V_L \end{pmatrix} \right\}$ $\| \begin{pmatrix} V_C \\ V_L \end{pmatrix} \|^2 = CV_C^2 + \frac{1}{L}V_L^2$

$\| \alpha(V_0) \|^2 = \| \begin{pmatrix} V_0 \\ V_0 \end{pmatrix} \|^2 = (C + L^{-1})V_0^2$

$\| \alpha_+ V_0 \|^2 = CV_0^2$ $\| \alpha_- V_0 \|^2 = L^{-1}V_0^2$

l''

Try again.

$$\bar{C}^0 \xrightarrow{\alpha} \begin{pmatrix} C_C' \\ C_L' \end{pmatrix}$$

$$V_0 \mapsto \begin{pmatrix} V_C \\ V_L \end{pmatrix}$$

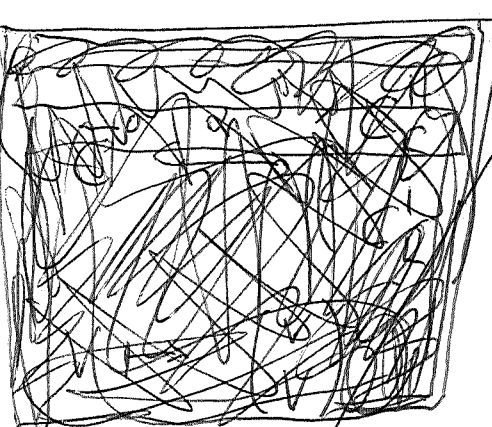
$$\begin{pmatrix} \alpha V_0 \\ V_C \\ V_L \end{pmatrix} = \begin{pmatrix} V_C \\ V_L \end{pmatrix} \begin{pmatrix} C & \\ & L' \end{pmatrix} \begin{pmatrix} V_C \\ V_L \end{pmatrix} = V_C C V_C + V_L L' V_L = V_0 (C V_C + L' V_L)$$

$$\therefore \alpha^* = (C \quad L^{-1})$$

$$\bar{C}^0 \xrightarrow{\alpha} \begin{pmatrix} C_C' \\ C_L' \end{pmatrix} \begin{pmatrix} V_C \\ V_L \end{pmatrix}$$

C

$$\left\| \begin{pmatrix} V_C \\ V_L \end{pmatrix} \right\|^2 = \begin{pmatrix} V_C \\ V_L \end{pmatrix}^* \begin{pmatrix} C & 0 \\ 0 & L' \end{pmatrix} \begin{pmatrix} V_C \\ V_L \end{pmatrix} = V_C C V_C + V_L L' V_L$$



$$\bar{C}^0 \xrightarrow{\alpha = \begin{pmatrix} 1 \\ 1 \end{pmatrix}} \begin{pmatrix} C_C' \\ C_L' \end{pmatrix} \xrightarrow{\begin{pmatrix} C^{1/2} \\ L^{-1/2} \end{pmatrix}} \begin{pmatrix} R \\ R \end{pmatrix}$$

$$\begin{pmatrix} V_C \\ V_L \end{pmatrix} \mapsto \begin{pmatrix} C^{+1/2} V_C \\ L^{-1/2} V_L \end{pmatrix}$$

$$\bar{C}^0 \xrightarrow{\begin{pmatrix} C^{1/2} \\ L^{-1/2} \end{pmatrix}} \begin{pmatrix} R \\ R \end{pmatrix}$$

$$V_0 \mapsto \begin{pmatrix} C^{1/2} \\ L^{-1/2} \end{pmatrix} V_0 \mapsto C V_0^2 + L^{-1} V_0^2$$

m''

~~Return to $\bar{C}^0 \hookrightarrow C_C' \oplus C_L'$ with the~~

~~pos quad form $\begin{pmatrix} V_C \\ V_L \end{pmatrix}^* \begin{pmatrix} C & 0 \\ 0 & L' \end{pmatrix} \begin{pmatrix} V_C \\ V_L \end{pmatrix} = V_C^* C V_C + V_L^* L' V_L$~~

~~on C_C' . Aim to split into eigenspaces. But first you want the dot product in a standard form.~~

~~Put $V_C = C^{-1/2} X_+$, $V_L = L'^{+1/2} X_-$~~

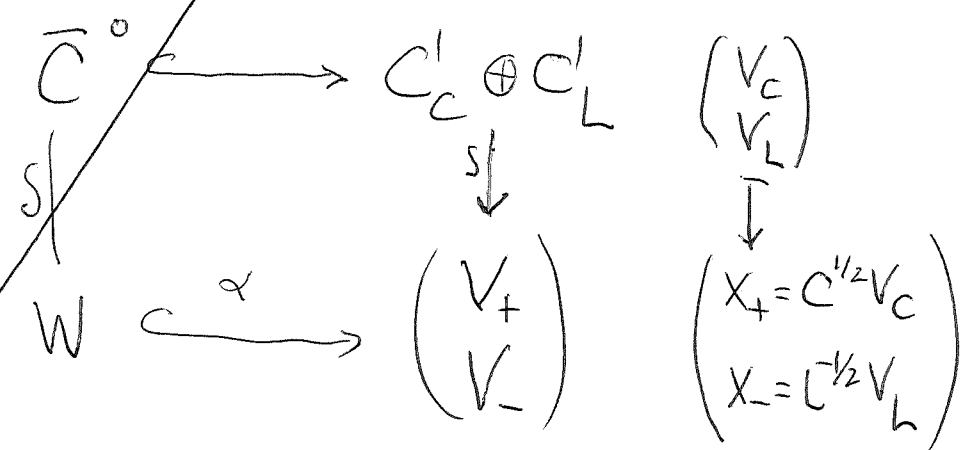
$$\begin{pmatrix} V_C \\ V_L \end{pmatrix} = \begin{pmatrix} C^{-1/2} & 0 \\ 0 & L'^{+1/2} \end{pmatrix} \begin{pmatrix} X_+ \\ X_- \end{pmatrix}$$

~~Then $\begin{pmatrix} V_C \\ V_L \end{pmatrix}^* \begin{pmatrix} V_C \\ V_L \end{pmatrix} = \begin{pmatrix} X_+ \\ X_- \end{pmatrix}^* \begin{pmatrix} C^{-1/2} & 0 \\ 0 & L'^{+1/2} \end{pmatrix} \begin{pmatrix} C^{-1/2} & 0 \\ 0 & L'^{+1/2} \end{pmatrix} \begin{pmatrix} X_+ \\ X_- \end{pmatrix}$~~

Put $X_+ = C^{+1/2} V_C$

$X_- = L'^{-1/2} V_L$

$$\begin{pmatrix} V_C \\ V_L \end{pmatrix}^* \begin{pmatrix} C & \\ & L' \end{pmatrix} \begin{pmatrix} V_C \\ V_L \end{pmatrix} = X_+^* X_+ + X_-^* X_-$$



In the s.h.o. case $\bar{C}^0 = \{V_0\}$

$$\alpha V_0 = \begin{pmatrix} V_0 \\ V_0 \end{pmatrix} \mapsto \begin{pmatrix} C^{+1/2} V_0 \\ L'^{-1/2} V_0 \end{pmatrix}$$

n''

$$\begin{aligned} \mathbb{C}^0 & \xrightarrow{(1)} \begin{pmatrix} \mathbb{R} \\ \mathbb{R} \end{pmatrix} \\ & \downarrow \begin{pmatrix} C^{1/2} & 0 \\ 0 & L^{-1/2} \end{pmatrix} \\ \mathbb{R} & \xrightarrow{\alpha = \begin{pmatrix} C^{1/2} \\ L^{-1/2} \end{pmatrix}} \begin{pmatrix} \mathbb{R} \\ \mathbb{R} \end{pmatrix} \end{aligned}$$

so you have the line $\frac{x}{y} = \frac{C^{1/2}}{L^{-1/2}} = \sqrt{LC}$ $y = \frac{x}{\sqrt{LC}}$

You want α isometric.

$$\alpha^* \alpha = \begin{pmatrix} C^{1/2} & L^{-1/2} \end{pmatrix} \begin{pmatrix} C^{1/2} \\ L^{-1/2} \end{pmatrix} = C + L^{-1}$$

so you change α to

$$\tilde{\alpha} = \begin{pmatrix} \sqrt{\frac{C}{C+L^{-1}}} \\ \sqrt{\frac{L^{-1}}{C+L^{-1}}} \end{pmatrix} = \begin{pmatrix} \sqrt{\frac{CL}{CL+1}} \\ \sqrt{\frac{1}{CL+1}} \end{pmatrix}$$

$$\tilde{\alpha} = \frac{1}{\sqrt{C+L^{-1}}} \begin{pmatrix} C^{1/2} \\ L^{-1/2} \end{pmatrix}$$

~~What does all this mean?~~ What does all this mean?

Keep on refreshing your memory. Reps of $\langle F, \varepsilon \rangle$

V f.d. Hilb $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$, $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, $F = +1$

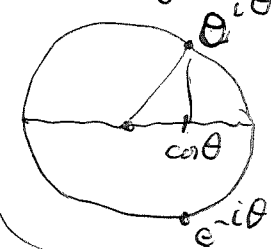
on W , -1 on W^\perp .

$g = F\varepsilon$ unitary, ~~What does all this mean?~~

$$V_\theta = \text{Ker}(g - e^{i\theta})$$

$$g \xi = e^{i\theta} \xi \Rightarrow g^{-1} \xi = e^{-i\theta} \xi$$

$$\therefore \varepsilon: V_\theta \xrightarrow{\sim} V_{-\theta}$$



What can you say if $\cos \theta \in (-1, 1)$?

say if ~~What does all this mean?~~ $\cos \theta$

$$V = \begin{pmatrix} V_\theta \\ V_{-\theta} \end{pmatrix} ?$$

0" Consider f.d. unitary repn^V of $\langle F, \varepsilon \rangle$. Have
 $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ $g = F\varepsilon$ unitary

let $V_\theta = \{ \xi \in V \mid g\xi = e^{i\theta}\xi \}$ $\Rightarrow \varepsilon V_\theta = V_{-\theta}$

$\Rightarrow V_\theta + V_{-\theta}$ stable under ε, g \therefore under F

~~Restrict to $V_\theta + V_{-\theta}$~~

Restrict $e^{i\theta} \neq \pm 1$ say $0 < \theta < \pi$. $\Rightarrow V = \begin{pmatrix} V_\theta \\ V_{-\theta} \end{pmatrix}$ $g \mapsto \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$ $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$$\begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$$

You want to conclude that ~~if~~ if $V = V_\theta \oplus V_{-\theta}$ then have isom.

$$(V, F, \varepsilon) \simeq \begin{pmatrix} V_+ \\ V_- \end{pmatrix}, \varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, F = \begin{pmatrix} c & s \\ s & -c \end{pmatrix}$$

~~$\frac{1}{2i} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix} \begin{pmatrix} i & -1 \\ i & 1 \end{pmatrix}$~~

$$= \frac{1}{2i} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} e^{i\theta}i & -e^{i\theta} \\ e^{-i\theta}i & e^{-i\theta} \end{pmatrix} = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$$

$$P'' = \frac{1}{2i} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} g & 0 \\ 0 & g^{-1} \end{pmatrix} \begin{pmatrix} i & -1 \\ i & 1 \end{pmatrix}$$

$$= \frac{1}{2i} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} gi & -g \\ g^{-1}i & +g^{-1} \end{pmatrix} = \frac{1}{2i} \begin{pmatrix} (g+g^{-1})i & -g+g^{-1} \\ g-g^{-1} & i(g+ig^{-1}) \end{pmatrix}$$

$$= \begin{pmatrix} \frac{g+g^{-1}}{2} & -\frac{g-g^{-1}}{2i} \\ \frac{g-g^{-1}}{2i} & \frac{g+g^{-1}}{2} \end{pmatrix}$$

You have a vague feeling that ~~the phase~~ the phase of $\frac{g-g^{-1}}{2}$ ~~should~~ ^{might} be significant

Repeat.

~~Given a unitary f.d. rep V of $\langle F, \varepsilon \rangle$, get~~

Given a unitary f.d. rep V of $\langle F, \varepsilon \rangle$, get $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$, $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, ~~and~~ put $g = F\varepsilon$

Look at $F=1$ subspace W of V . Assume

$g+1$ invertible. ~~Then~~ Then it should be true that

$$W = \begin{pmatrix} 1 \\ T \end{pmatrix} V_+ \quad W^\perp = \begin{pmatrix} -T^* \\ 1 \end{pmatrix} V_- \quad g = \begin{pmatrix} 1 & X \\ -1 & 1 \end{pmatrix} X$$

$$F \begin{pmatrix} 1 & -T^* \\ T & 1 \end{pmatrix} = \begin{pmatrix} 1 & -T^* \\ T & 1 \end{pmatrix} \varepsilon$$

$$F\varepsilon = \frac{1+X}{1-X}$$

$$\frac{g+g^{-1}}{2} = \frac{1}{2} \left(\frac{1+2X+X^2 + 1-2X+X^2}{1-X^2} \right) = \frac{1+X^2}{1-X^2}$$

$$X = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} g = \frac{g-1}{g+1}$$

$$\frac{g-g^{-1}}{2i} = \frac{1}{2i} \left(\frac{1+2X+X^2 - 1+2X-X^2}{1-X^2} \right) = \frac{1}{i} \frac{2X}{1-X^2}$$

$$g+1 = \frac{1+X}{1-X} + 1 = \frac{2}{1-X}$$

g'' It's ~~time~~ time to organize the possibilities

Given a f.d. unitary rep of $\langle F, \varepsilon \rangle$ on V .

$$V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \quad \varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Put $g = F\varepsilon$ which is unitary. Let $V_\theta = \{\xi \in V \mid g\xi = e^{i\theta}\xi\}$. Since $\varepsilon: V_\theta \rightarrow V_{-\theta}$,

$V_\theta + V_{-\theta}$ is stable under $\langle g, \varepsilon \rangle = \langle F, \varepsilon \rangle$.

Replace $e^{i\theta}$ by ζ , so $V_\zeta = g$ -eigenspace eigenvalue ζ

First case $\zeta = \zeta^{-1} \quad \zeta = \pm 1$. Then $V_\zeta = V_{\zeta^{-1}}$ etc.

Otherwise $V = \begin{pmatrix} V_{e^{i\theta}} \\ V_{e^{-i\theta}} \end{pmatrix}$, $F \mapsto \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$, $\varepsilon \mapsto \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

Now put back $\zeta = e^{i\theta}$

$$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} =$$

$$= \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$$

~~$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} = \begin{pmatrix} -i & i \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} -i & i \\ 1 & 1 \end{pmatrix}$$~~

$$\frac{1}{2i} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} = \frac{1}{2i} \begin{pmatrix} 1 & -1 \\ i & 1 \end{pmatrix} \begin{pmatrix} -i & i \\ 1 & 1 \end{pmatrix}$$

$$= \frac{1}{2i} \begin{pmatrix} \dots & \dots \\ \dots & \dots \end{pmatrix}$$

$$\begin{aligned} & \frac{1}{2i} \begin{pmatrix} i & -1 \\ i & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \\ &= \frac{1}{2i} \begin{pmatrix} i & -1 \\ i & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix} = \frac{1}{2i} \begin{pmatrix} 0 & 2i \\ 2i & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \end{aligned}$$

V unit^{fd.} rep of $\langle F, \varepsilon \rangle$ $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$F_\varepsilon = g$ unitary $V_\theta = \{ \xi \in V \mid g\xi = e^{i\theta}\xi \}$

$\varepsilon: V_\theta \xleftrightarrow{\sim} V_{-\theta}$ $\begin{pmatrix} V_\theta \\ V_{-\theta} \end{pmatrix}$ stable under ε, g

$g \mapsto \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$ $\varepsilon \mapsto \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$?

where to start. Think of ε fixed, ~~and~~
and $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ with $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ and

$$g_\theta = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$$

$$\begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ i & -i \end{pmatrix}$$

s" Now start again. Study unitary repr
 (V, F, ε) . Write $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ with $\varepsilon \mapsto \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$.

Put $g = F\varepsilon$. g is unitary.

Put $V_\theta = \{ \xi \in V \mid g\xi = e^{i\theta}\xi \}$. $\varepsilon: V_\theta \xrightarrow{\sim} V_{-\theta}$

~~Let~~ Let ξ be a unit vector in V_θ . Then
 $\mathbb{C}\xi + \mathbb{C}\varepsilon\xi \subset V$ stable under ε, g , hence also F .
 irred rep. for $\theta \in (0, \pi)$. ~~If $e^{i\theta} = \pm 1$,~~
 then $\xi, \varepsilon\xi$ ~~are~~

Suppose $g\xi = \xi$. ~~then~~ i.e. $\xi \in V_0$

then $\varepsilon\xi \in V_0$. So g fixes $\xi, \varepsilon\xi$. ~~If g is~~
~~not an irred repn~~ so $g = 1$ and $F = \varepsilon = \pm 1$
 on $\mathbb{C}\xi + \mathbb{C}\varepsilon\xi$, get 2 characters. Sim. for $\theta = \pi$

$$g\xi = -\xi \implies g^{-1}\varepsilon\xi = -\varepsilon\xi \implies g \begin{pmatrix} \xi \\ \varepsilon\xi \end{pmatrix} = \begin{pmatrix} -\xi \\ -\varepsilon\xi \end{pmatrix}, \quad g^{-1}$$

So you have irred 2 diml reps.

$$g = \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$$

$$\varepsilon = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$F = \begin{pmatrix} 0 & e^{i\theta} \\ e^{-i\theta} & 0 \end{pmatrix}$$

which you can conj to

$$g = \begin{pmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{pmatrix}$$

$$\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$F = \begin{pmatrix} \cos & \sin \\ \sin & -\cos \end{pmatrix}$$

~~Let~~ $\begin{pmatrix} \frac{g+g^{-1}}{2} & -\frac{g-g^{-1}}{2i} \\ \frac{g-g^{-1}}{2i} & \frac{g+g^{-1}}{2} \end{pmatrix} \begin{pmatrix} -1 & 1 \\ -i & i \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ -i & i \end{pmatrix} \begin{pmatrix} g & 0 \\ 0 & g^{-1} \end{pmatrix}$

t'' Given V f.d. unitary repr of $\langle F, \varepsilon \rangle$

splitting $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \quad \varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$g = F\varepsilon \quad \begin{pmatrix} \frac{1}{2}(g+g^{-1}) & -\frac{g-g^{-1}}{2i} \\ \frac{g-g^{-1}}{2i} & \frac{1}{2}(g+g^{-1}) \end{pmatrix} \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$

Is this well defined on V ?

You are given on V two ^{unitary} operators $\varepsilon: \varepsilon^2 = 1$, and g s.t. $\varepsilon g \varepsilon^{-1} = g^{-1}$. From ε you get

$\text{Hom}(V, V) = \begin{matrix} \text{Hom}(V_+, V_+) & \text{Hom}(V_+, V_-) \\ \text{Hom}(V_-, V_+) & \text{Hom}(V_-, V_-) \end{matrix}$

$\begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{\begin{pmatrix} \frac{1+\varepsilon}{2} & \\ & \frac{1-\varepsilon}{2} \end{pmatrix} g \begin{pmatrix} \frac{1+\varepsilon}{2} & \\ & \frac{1-\varepsilon}{2} \end{pmatrix}} \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$

$\frac{1+\varepsilon}{2} g \frac{1+\varepsilon}{2} = \frac{g + \varepsilon g + g \varepsilon + g^{-1}}{4}$

It seems that you have too much.

Take V to be irreducible $V = \begin{pmatrix} \mathbb{C} \\ \mathbb{C} \end{pmatrix} \quad \sigma = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$g = \begin{pmatrix} a & -s \\ s & c \end{pmatrix}$

$F = \begin{pmatrix} \frac{1}{2}(g+g^{-1}) & -\frac{g-g^{-1}}{2i} \\ \frac{g-g^{-1}}{2i} & -\frac{1}{2}(g+g^{-1}) \end{pmatrix} \quad X = \begin{pmatrix} 0 & -T^* \\ T & 0 \end{pmatrix}$

$g = \frac{1+X}{1-X}$

$g^{1/2} = \frac{1+X}{\sqrt{1-X^2}}$

$\frac{1+\cos \theta}{2} = \cos^2 \frac{\theta}{2}$

$\frac{1-\cos \theta}{2} = \sin^2 \frac{\theta}{2}$

u¹¹

$$F \oplus (1+X) = (1+X) \varepsilon = \varepsilon (1-X)$$

$$\frac{1+X}{1-X} = F \varepsilon = g \quad F = \frac{1+X}{1-X} \varepsilon$$

$$g^{1/2} = \frac{1+X}{\sqrt{1-X^2}}$$

$$g^{1/2} \varepsilon g^{-1/2} = g \varepsilon = F$$

\oint $g = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ then $F = \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix}$

$$\frac{1+F}{2} = \begin{pmatrix} \cos^2 \frac{\theta}{2} & \sin \frac{\theta}{2} \cos \frac{\theta}{2} \\ \cos \frac{\theta}{2} \sin \frac{\theta}{2} & \sin^2 \frac{\theta}{2} \end{pmatrix} = \begin{pmatrix} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{pmatrix} \begin{pmatrix} \cos \frac{\theta}{2} & \sin \frac{\theta}{2} \end{pmatrix}$$

$$\frac{1+F}{2} = \begin{pmatrix} \frac{1}{2}(1 + \frac{1}{2}(g+g^{-1})) & \frac{1}{2} \frac{g-g^{-1}}{2i} \\ \frac{1}{2} \frac{g-g^{-1}}{2i} & \frac{1}{2}(1 - \frac{1}{2}(g+g^{-1})) \end{pmatrix} = \begin{pmatrix} \frac{g^{1/2} + g^{-1/2}}{2} \\ \frac{g^{1/2} - g^{-1/2}}{2i} \end{pmatrix} \begin{pmatrix} \frac{g^{1/2} + g^{-1/2}}{2} & \frac{g^{1/2} - g^{-1/2}}{2i} \end{pmatrix}$$

$$\frac{g^{1/2} + g^{-1/2}}{2} = \frac{1+X + 1-X}{2(1-X^2)^{1/2}} = \frac{1}{\sqrt{1-X^2}}$$

$$\frac{g^{1/2} - g^{-1/2}}{2i} = \frac{1}{2i} \frac{1+X - (1-X)}{(1-X^2)^{1/2}} = \frac{1}{i} \frac{X}{\sqrt{1-X^2}}$$

$$\begin{pmatrix} 1 \\ \frac{1}{i} X \end{pmatrix} \frac{1}{1-X^2} \begin{pmatrix} 1 & \frac{1}{i} X \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

V'' So what ~~are~~ are you doing.

(Repr) unitary_n of $\langle F, \varepsilon \rangle$ on V , write $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$
 with $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, ~~we~~ have $g = F\varepsilon$ unitary

$$\begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{g} \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$$

$$g = \underbrace{\frac{g+g^{-1}}{2}}_{\text{even}} + i \underbrace{\frac{g-g^{-1}}{2i}}_{\text{odd}}$$

$$\begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{\begin{pmatrix} L_+^* \\ L_-^* \end{pmatrix}} V \xleftarrow{g} V \xleftarrow{\begin{pmatrix} L_+ \\ L_- \end{pmatrix}} \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$$

$$\begin{pmatrix} L_+^* g L_+ & L_+^* g L_- \\ L_-^* g L_+ & L_-^* g L_- \end{pmatrix}$$

L_+

+ comp

~~should~~ L_+ L_+ should satisfy orthog relns.

$$\begin{pmatrix} L_+^* \\ L_-^* \end{pmatrix} \begin{pmatrix} L_+ & L_- \end{pmatrix} = \begin{pmatrix} 1_+ & 0 \\ 0 & 1_- \end{pmatrix}$$

$$\begin{pmatrix} L_+ & L_- \end{pmatrix} \begin{pmatrix} L_+^* \\ L_-^* \end{pmatrix} = I_V$$

~~Try again.~~

Try again. Unitary repr of

Assume $\frac{g+g^{-1}}{2} = (\cos \theta) \text{Id}$

where $\theta \in (0, \pi)$. Does it follow that $\frac{g-g^{-1}}{2i} = (\sin \theta) \text{Id}$?

Seems not. Let's understand this well.

$$V = \mathbb{C}^2$$

$$\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$F = \begin{pmatrix} \cos \theta + i \sin \theta & \\ \sin \theta & -\cos \theta \end{pmatrix}$$

W'' Consider again a unitary repn of $\langle F, \varepsilon \rangle$ on V finite dimensional. Use ε to get splitting

$$V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \text{ with } \varepsilon \mapsto \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \quad \text{Let}$$

$$V = W \oplus W^\perp \quad \text{where } F = +1 \text{ on } W \\ = -1 \text{ on } W^\perp$$

$$\begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{\begin{pmatrix} a & b \\ c & d \end{pmatrix}} \begin{pmatrix} W \\ W^\perp \end{pmatrix} \xleftarrow{\quad} \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \xleftarrow{\quad} \begin{pmatrix} W \\ W^\perp \end{pmatrix} ?$$

$$W \hookrightarrow \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \longrightarrow W^\perp$$

$$\longrightarrow \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$$

Consider $V = \begin{pmatrix} \mathbb{C} \\ \mathbb{C} \end{pmatrix}$ $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, let W be

a line in V , $W = \begin{pmatrix} 1 \\ T \end{pmatrix} \mathbb{C}$ $T \in \mathbb{C}$

$$W^\perp = \begin{pmatrix} -\bar{T} \\ 1 \end{pmatrix} \mathbb{C}$$

$$F = \begin{cases} 1 & \text{on } W \\ -1 & \text{on } W^\perp \end{cases} \quad F \begin{pmatrix} 1 & -\bar{T} \\ T & 1 \end{pmatrix} = \begin{pmatrix} 1 & -\bar{T} \\ T & 1 \end{pmatrix} \varepsilon$$

$$F(1+X) = (1+X)\varepsilon = \varepsilon(1-X) \quad \frac{1+X}{1-X} = F\varepsilon$$

Why not simplify by doing real case.

x''

$$V = \begin{pmatrix} \mathbb{R} \\ \mathbb{R} \end{pmatrix}, \quad \varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \quad W \text{ a line in } V$$

$W = \mathbb{R} \begin{pmatrix} x \\ y \end{pmatrix}$ where $x^2 + y^2 = 1$. $\begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} -x \\ -y \end{pmatrix}$
 yield the same line. $W^\perp = \begin{pmatrix} -y \\ x \end{pmatrix} \mathbb{R}$

$$F \begin{pmatrix} x & -y \\ y & x \end{pmatrix} = \begin{pmatrix} x & -y \\ y & x \end{pmatrix} \varepsilon = \varepsilon \begin{pmatrix} x & y \\ -y & x \end{pmatrix}$$

$$\begin{pmatrix} x & -y \\ y & x \end{pmatrix} \begin{pmatrix} x & y \\ -y & x \end{pmatrix}^{-1} = F \varepsilon = g$$

$$\begin{pmatrix} x & -y \\ y & x \end{pmatrix} \begin{pmatrix} x & -y \\ y & x \end{pmatrix} \frac{1}{x^2 + y^2}$$

$$\frac{1+F}{2} = \begin{pmatrix} x \\ y \end{pmatrix} \frac{1}{x^2 + y^2} \begin{pmatrix} x & y \end{pmatrix}$$

$$\frac{1-F}{2} = \begin{pmatrix} -y \\ x \end{pmatrix} \frac{1}{x^2 + y^2} \begin{pmatrix} -y & x \end{pmatrix}$$

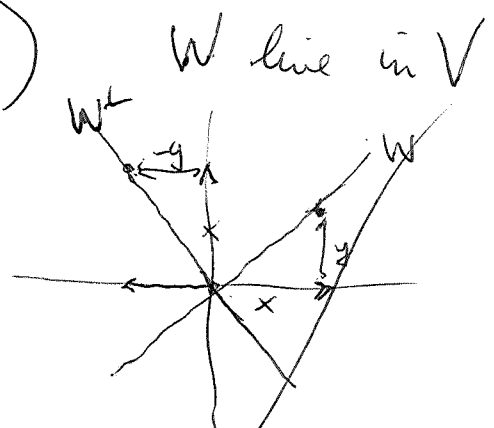
$$g = \begin{pmatrix} x^2 - y^2 & -2xy \\ 2xy & x^2 - y^2 \end{pmatrix} \frac{1}{x^2 + y^2}$$

$$F = \begin{pmatrix} \frac{x^2 - y^2}{x^2 + y^2} & \frac{+2xy}{x^2 + y^2} \\ \frac{2xy}{x^2 + y^2} & \frac{-x^2 + y^2}{x^2 + y^2} \end{pmatrix}$$

$$F \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \frac{x^2 - y^2}{x^2 + y^2} x + \frac{2xy}{x^2 + y^2} y \\ \frac{2x^2 y}{x^2 + y^2} + \frac{-x^2 + y^2}{x^2 + y^2} y \end{pmatrix} = \frac{1}{x^2 + y^2} \begin{pmatrix} x^3 - y^2 x + 2xy^2 \\ 2x^2 y - x^2 y + y^3 \end{pmatrix}$$

y'' $V = \begin{pmatrix} \mathbb{R} \\ \mathbb{R} \end{pmatrix}$ $E = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ W line in V

$W = \begin{pmatrix} x \\ y \end{pmatrix} \mathbb{R}$, $W^\perp = \begin{pmatrix} -y \\ x \end{pmatrix} \mathbb{R}$



What ~~exactly~~ do you want? ~~What~~

You have

$W \xleftrightarrow{i} \begin{pmatrix} \mathbb{R} \\ \mathbb{R} \end{pmatrix} \xleftrightarrow{j} W^\perp$

On $V = \begin{pmatrix} \mathbb{R} \\ \mathbb{R} \end{pmatrix}$ you have the quadratic form

$\begin{pmatrix} x \\ y \end{pmatrix}^T \begin{pmatrix} s & \\ & s^{-1} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = sx^2 + s^{-1}y^2 = A_s \begin{pmatrix} x \\ y \end{pmatrix}$

~~Let's use~~ Let's use equip W with the ~~inner~~ inner product induced from V , also W^\perp . This is just the restriction of A_s for $s=1$. ~~What is~~

~~unit vector gen.~~ unit vector gen. W is

$\frac{1}{\sqrt{x^2+y^2}} \begin{pmatrix} x \\ y \end{pmatrix}$. Restriction of A_s is

$A_s \left(\frac{t}{\sqrt{x^2+y^2}} \begin{pmatrix} x \\ y \end{pmatrix} \right) = \frac{t^2}{x^2+y^2} (sx^2 + s^{-1}y^2)$

What's important here is that you have

$\frac{x^2}{x^2+y^2} s + \frac{y^2}{x^2+y^2} s^{-1}$

You recall ^{introducing a} ~~frequency~~ frequency variable ω . Something like

$\frac{s^2 + \omega^2}{s(1+\omega^2)} = \frac{1}{1+\omega^2} s + \frac{\omega^2}{1+\omega^2} s^{-1}$

are ≥ 0 + add to 1

$\frac{1}{1 + \left(\frac{y}{x}\right)^2} s + \frac{\left(\frac{y}{x}\right)^2}{1 + \left(\frac{y}{x}\right)^2} s^{-1}$

z'' So you learn that the C.T. picture of the Grassmannian is related to the frequency variable s .

For example: Given $W \hookrightarrow \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$ better $W = \begin{pmatrix} 1 \\ T \end{pmatrix} V_+ \subset \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$

then you should an isometric

$$V_+ \xrightarrow{\begin{pmatrix} 1 \\ T \end{pmatrix}} \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \quad (1 \ T^*) \begin{pmatrix} 1 \\ T \end{pmatrix} = 1 + T^*T$$

$$V_+ \xrightarrow{\begin{pmatrix} 1 \\ T \end{pmatrix} (1 + T^*T)^{-1/2}} \begin{pmatrix} V_+ \\ V_- \end{pmatrix} \quad \alpha_+ = (1 + T^*T)^{-1/2}$$

$$\alpha_- = T(1 + T^*T)^{-1/2}$$

check $\alpha_+^* \alpha_+ = (1 + T^*T)^{-1/2} (1 + T^*T)^{-1/2} = \frac{1}{1 + T^*T}$

$$\alpha_-^* \alpha_- = (1 + T^*T)^{-1/2} T^* T (1 + T^*T)^{-1/2} = \frac{T^*T}{1 + T^*T}$$

~~What is then~~ The induced quadratic form on $W = \begin{pmatrix} 1 \\ T \end{pmatrix} V_+$

should be $(\alpha_+^* \ \alpha_-^*) \begin{pmatrix} s & 0 \\ 0 & s^{-1} \end{pmatrix} \begin{pmatrix} \alpha_+ \\ \alpha_- \end{pmatrix} = \frac{s}{1 + T^*T} + \frac{1}{s} \frac{T^*T}{1 + T^*T}$

$$= \frac{s^2 + T^*T}{s(1 + T^*T)}$$

think of T as $\tan \theta$

Then $\begin{pmatrix} 1 \\ \tan \theta \end{pmatrix} \frac{1}{\sec \theta} = \begin{pmatrix} 1 \\ \tan \theta \end{pmatrix} \cos \theta = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}$

Question. Given ~~W~~ $V = \begin{pmatrix} V_+ \\ V_- \end{pmatrix}$, $\varepsilon = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, F

$$g = F\varepsilon$$

$$\begin{pmatrix} \frac{g + g^{-1}}{2} & -\frac{g - g^{-1}}{2i} \\ \frac{g - g^{-1}}{2i} & \frac{g + g^{-1}}{2} \end{pmatrix}$$

this should have an obvious meaning on $\begin{pmatrix} V_+ \\ V_- \end{pmatrix}$

Restricted to case $\frac{g + g^{-1}}{2} = (\cos \theta) Id$

Question Anything special about $F\varepsilon$ rather than εF