

January 13, 1979

Dirac with δ -potential.

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Let's try to reconcile LS and Lax-Phillips in the case of a radial Dirac system, which we write in the form

$$\frac{d\psi}{dx} = ik\psi + V\psi$$

where

$$(V\psi)(x) = h(x)\psi(-x)$$

and h satisfies

$$h(-x) = -\overline{h(x)}$$

so that iV is hermitian. Then

$$(I - G_k^+ V)\psi(x) = \psi(x) - \int_{-\infty}^x e^{ik(x-x')} (V\psi)(x') dx'.$$

Recall the way we computed $\det(I - G_k^+ V)$. We note that $G_k^+ V$ is supported to the right of the obstacle, and that

$$\left(\frac{d}{dx} - ik \right) (I - G_k^+ V) = \frac{d}{dx} - ik - V$$

If we denote by A_0 the operator induced on $L^2(a, \infty)$ by $\frac{d}{dx}$ with domain cut down to f with $f(a) = 0$, then G_k^+ is simply $(A_0 - ik)^{-1}$, and

$$I - G_k^+ V = (A_0 - ik)^{-1} (A - ik)$$

Finally A_0^{-1} is a Volterra operator

$$A_0^{-1} f = \int_a^x f(x') dx'$$

so

$$I - G_k^+ V = (1 - ik A_0^{-1})^{-1} (A_0^{-1} A) (I - i k A^{-1})$$

where I assume that A^{-1} exists. Now

$$\det(1 - ikA_0^{-1}) = 1$$

so

$$\det(1 - G_k^+ V) = \det(A_0^{-1} A) \det(1 - ikA^{-1}).$$

Here A denotes the operator $\frac{d}{dx} - V$ on $L^2(a, \infty)$ with domain restricted to f vanishing at a ; hence $A = A_0 - V$. The basic determinant we are after is $\det(1 - ikA^{-1}) = \det(1 - k\tilde{H}^{-1})$ where $\tilde{H} = \frac{1}{i}A$, is the operator on $L^2(a, \infty)$ generating the semi-group of contractions.

What is the Lax-Phillips approach? Let $D = L^2(a, \infty)$, $D' = L^2(b, \infty)$ where V is supported between a, b . To be precise one replaces the Hilbert space by solutions of the wave equation

$$\frac{\partial \tilde{\psi}}{\partial x} = - \frac{\partial \tilde{\psi}}{\partial t} + V \tilde{\psi}$$

by associating to any $u \in L^2(\mathbb{R})$, the solution of the wave equation beginning at u at $t=0$. Then elements of D correspond to solutions $\tilde{\psi}(x, t)$ vanishing for $x < t$, $t \leq 0$, and D' corresponds to solutions supported in $[b+t, \infty)$ for $t \geq 0$.

Let us next shift to the stationary picture which means that we Fourier transform solutions of the wave equation with respect to time.

$$\tilde{\psi}(x, t) = \int e^{-ikt} \psi(x, k) dk / 2\pi$$

Then we have the scattering

$$e^{ikx} \longleftrightarrow R(k) e^{ikx}$$

Denote the eigenfunction with above behavior by $\phi(x, k)$, so that solutions of the wave equation are given by

$$\psi(x, k) = \alpha(k) \phi(x, k)$$

Then $\psi \in D$ means that for $x < t+a$, $t \leq 0$

$$\int_{-\infty}^{\infty} e^{-ikt} e^{ikx} \alpha(k) dk = 0$$

$$\forall \varepsilon > 0 \quad \int e^{+ika} \alpha(k) e^{-ik\varepsilon} dk = 0 \Rightarrow e^{+ika} \alpha \in H^-$$

$$\text{or } \alpha \in e^{-ika} H^-$$

similarly $\psi \in D'$ means that for $b < x < b+t$, $t \geq 0$
one  has

$$\int \underbrace{e^{-ikt} e^{ikx}}_{e^{ikb} e^{-ik\varepsilon}} R(k) \alpha(k) dk = 0$$

$$\text{or } R(k) \alpha(k) \in e^{-ikb} H^-$$

so therefore

$$D \simeq e^{-ika} H^-$$

$$D' \simeq e^{-ikb} R^{-1} H^-$$

$$D/D' \simeq H^- / e^{-ik(b-a)} R^{-1} H^-$$

Now when the original system comes from a Dirac

system pieced end to end we have

$$A(k)e^{ikx} \longleftrightarrow B(k)e^{-ikx}$$

where $B(k) = \overline{A(\bar{k})}$, and $a = -b$, and so

$$R = \frac{B(k)}{A(k)}$$

Thus if we revert to a simpler notation

$$\overline{(D/D')} \simeq H^+ / e^{ik2b} \frac{B}{A} H^+ \quad T(t) = \text{mult. by } e^{ikt}$$

Now A is non-vanishing on the UHP, so only the zeroes of B matter.

Now the problem is to compute the characteristic polynomial of the infinitesimal generator of the semi-group $T(t)$.

Example: suppose we consider

$$(u_1)(x) = \begin{pmatrix} e^{ikx} & 0 \\ 0 & e^{-ikx} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \text{for } 0 \leq x < \varepsilon$$

then

$$= \begin{pmatrix} e^{ik(x-\varepsilon)} & 0 \\ 0 & e^{-ik(x-\varepsilon)} \end{pmatrix} \frac{1}{k} \begin{pmatrix} 1 & -h \\ -\bar{h} & 1 \end{pmatrix} \begin{pmatrix} e^{ik\varepsilon} & 0 \\ 0 & e^{-ik\varepsilon} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \text{for } x > \varepsilon$$

$$= \begin{pmatrix} e^{ikx} & 0 \\ 0 & e^{-ikx} \end{pmatrix} \frac{1}{k} \begin{pmatrix} 1 & -he^{-2ik\varepsilon} \\ -\bar{h}e^{2ik\varepsilon} & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} B(k)e^{ikx} \\ A(k)e^{-ikx} \end{pmatrix} \quad B(k) = \frac{1}{\sqrt{1-h^2}}(1-he^{-2ik\varepsilon})$$

$$A(k) = \frac{1}{\sqrt{1-h^2}}(-\bar{h}e^{2ik\varepsilon} + 1)$$

so that

$$R(k) = \frac{B(k)}{A(k)} = e^{-2ik\varepsilon} \left(\frac{e^{2ik\varepsilon} - h}{-h e^{2ik\varepsilon} + 1} \right)$$

Now a convenient choice for b is ε . Then

$$e^{2ikb} R(k) = \frac{e^{2ik\varepsilon} - h}{-h e^{2ik\varepsilon} + 1}$$

and so $\mathcal{D}/\mathcal{D}' \simeq H^+ / (e^{2ik\varepsilon} - h) H^+$

and I have to compute a determinant, if the singularity in V doesn't interfere.

Let us try to understand $H^+ / (e^{ik} - h) H^+$
where $|h| < 1$. Recall

$$H^+ \simeq L^2(0, \infty)$$

$$\int_0^\infty e^{ikx} g(x) dx \longleftrightarrow g(x)$$

$$f(k) \longmapsto \int e^{-ikx} f(k) dk / 2\pi = \hat{f}(x)$$

so that

$$e^{ikt} f(k) \longmapsto \int e^{-ikx} e^{ikt} f(k) dk / 2\pi = \hat{f}(x-t)$$

Thus multiplying by e^{ikt} corresponds to the forward shift $\hat{f} \mapsto \hat{f}(x-t)$.

Let $f \in L^2(0, \infty) \simeq H^+$ be $\perp (e^{ik} - h) H^+$, i.e.

~~(T*)~~ $(T^* - h)f = 0$ where T^* is the adjoint of the shift $g(x) \mapsto g(x-1)$, which is $g(x) \mapsto g(x+1)$ restricted to $(0, \infty)$. Thus $f \in H^+ \cap (e^{ik} - h) H^+ \iff$

$$f(x+1) = \bar{h} f(x)$$

Thus $H^+/(e^{ik_0 x} H^+)$ can be identified with the subspace W ⁴⁸⁰ of $f \in L^2(0, \infty)$ satisfying $f(x+1) = \bar{h}f(x)$. This in turn is isomorphic to $L^2(0, 1)$ by restriction, but with norm

$$\begin{aligned}\|f\|_W^2 &= \|f\|_{(0, \infty)}^2 = \|f\|_{(0, 1)}^2 (1 + |h|^2 + |h|^4 + \dots) \\ &= \frac{\|f\|_{(0, 1)}^2}{1 - |h|^2}\end{aligned}$$

Let $f \in W$. Choose k_0 with $e^{ik_0} = \bar{h}$, whence the solutions of $e^{ikx} = \bar{h}$ are $k_n = k_0 + 2\pi n$ as $n \in \mathbb{Z}$. Also $e^{-ik_0 x} f(x)$ satisfies

$$e^{-ik_0(x+1)} f(x+1) = e^{-ik_0 x} f(x)$$

so it is periodic and hence admits a Fourier series expansion

$$\begin{aligned}e^{-ik_0 x} f(x) &= \sum a_n e^{2\pi i n x} \\ a_n &= \frac{1}{1} \int_0^1 f(x) e^{-ik_0 x} e^{-2\pi i n x} dx\end{aligned}$$

So

$$f(x) = \sum_{n \in \mathbb{Z}} a_n e^{ik_n x} \quad a_n = \frac{1}{1} \int_0^1 f(x) e^{-ik_n x} dx.$$

But

$$\begin{aligned}\int_0^\infty f(x) e^{-ik_n x} dx &= \sum_{j=0}^\infty \int_j^{j+1} f(x) e^{-ik_n x} dx \\ &= \sum_{j=0}^\infty \int_0^1 f(x+j) e^{-ik_n x} e^{-ik_n j} dx\end{aligned}$$

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$\mathcal{W} = H^+ \ominus (e^{ik} - h)H^+$ contains the point-evaluators at the zeroes of $e^{ik} - h$. Since

$$\hat{f}(k) = \int_0^\infty f(x) e^{ikx} dx$$

\mathcal{W} contains $e^{-i\bar{k}x}$ when $e^{+ik} = h$, i.e. $e^{-i\bar{k}} = \bar{h}$.

So again we see that \mathcal{W} contains e^{ikx} when $e^{ik} = h$.

Let's change notation slightly and denote by Λ
 $= \{k \mid e^{ik} = h\}$, so that \mathcal{W} is spanned by $e^{-i\bar{\lambda}x}$, $\lambda \in \Lambda$.

The evaluation map

$$f \mapsto \hat{f}(\lambda) = (f, e^{-i\bar{\lambda}x})$$

satisfies $f(x-t) \mapsto (e^{ikt}\hat{f})(\lambda) = e^{i\lambda t} \hat{f}(\lambda)$ for $t \geq 0$

so it ~~gives a projection~~ picks up the eigenspace for $T(t)$ corresponding to λ .

Now

$$(T(t)f, e^{-i\bar{\lambda}x}) = e^{i\lambda t} (f, e^{-i\bar{\lambda}x})$$

$$(f, T(t)^* e^{-i\bar{\lambda}x})$$

for all $f \in \mathcal{W}$, so that

$$T(t)^*(e^{-i\bar{\lambda}x}) = e^{-i\bar{\lambda}t} e^{-i\bar{\lambda}x}$$

hence

$$T(t)^*(f) = f(x+t) \quad \text{for all } f \in \mathcal{W}.$$

Hence $T(t)^*$ is diagonal with the eigenvalues $e^{-i\bar{\lambda}t}$
 $\lambda \in \Lambda$, I expect $T(t)$ to have the eigenvalues $e^{i\lambda t}$.

The infinitesimal generator iH of $\{T(t)\}$ has the eigenvalues 482
 $\{i\lambda, \lambda \in \Lambda\}$, and thus we form $1 - k H^{-1}$, which has
 the eigenvalues $1 - k/\lambda \quad \lambda \in \Lambda$ and so

$$\det(1 - k H^{-1}) = \prod_{\lambda \in \Lambda} (1 - k/\lambda)$$

The problem here is that this infinite product is not convergent without making an Eisenstein summation of some sort.

Question: Is there a well-defined LS determinant in this case?

January 15, 1979

Consider a Dirac system on $0 \leq x < \infty$

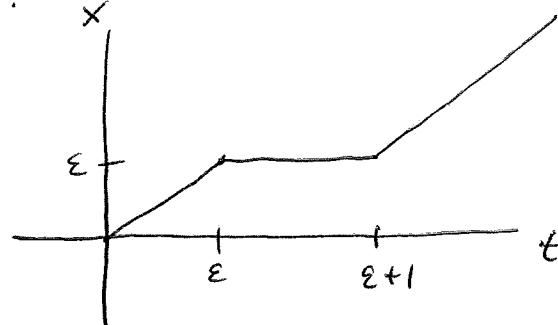
$$\frac{d}{dx} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} ik & p \\ \bar{p} & -ik \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$



$$u_1(0) = u_2(0)$$

where $p(x) = c \delta(x-\varepsilon)$.

In order to study this we introduce a new independent variable t :



$$x(t) = \begin{cases} t & 0 \leq t \leq \varepsilon \\ \varepsilon & \varepsilon \leq t \leq \varepsilon+1 \\ t-1 & \varepsilon+1 \leq t < \infty \end{cases}$$

and we write the above DE as

$$\frac{d}{dx} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} ik dx & pdx \\ \bar{p} dx & -ik dx \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

and replace pdx by $cX(t)dt$ where $X(t) = 1$ on $[\varepsilon, \varepsilon+1]$ and zero elsewhere. This makes sense since

$$\int_a^b pdx = \begin{cases} c & \varepsilon \in [a, b] \\ 0 & \varepsilon \notin [a, b] \end{cases}$$

Notice

$$\frac{dx}{dt} = 1 - X(t) \quad \text{a.e.}$$

Thus our DE becomes

$$\frac{d}{dt} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} ik \frac{dx}{dt} & cx(t) \\ -\bar{c}x(t) & -ik \frac{dx}{dt} \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}.$$

② We can ~~█~~ put this in the form

$$(*) \quad \frac{du}{dt}(t) = ik \frac{dx}{dt} \cdot u(t) + g(t) u(-t) \quad t \in \mathbb{R}$$

where

$$g(t) = \begin{cases} cx(t) & \text{for } t \geq 0 \\ -\bar{c}x(-t) & \text{for } t < 0. \end{cases}$$

and $x(-t) = -x(t)$.

Integrate ~~█~~ (*) using outgoing boundary conditions; which means $u=0$ for $t \ll 0$.

$$e^{-ik \int x(t) dt} - ik \frac{dx}{dt} u = e^{-ikx(t)} g(t) u(-t)$$

||

$$\frac{d}{dt} \left\{ e^{-ikx} u \right\}$$

$$e^{-ikx(t)} u(t) = \int_{-\infty}^t e^{-ikx(t')} g(t') u(-t') dt'$$

$$u(t) = e^{ik \int x(t) dt} \int_{-\infty}^t e^{-ikx(t')} g(t') u(-t') dt'$$

$$u(t) = e^{ikx(t)} \int_{-t}^{\infty} e^{ikx(t')} g(-t') u(t') dt'$$

Now the kernel

$$K(t, t') = \begin{cases} e^{-ik(x(t) + x(t'))} g(-t') & t + t' \geq 0 \\ 0 & t + t' < 0 \end{cases}$$

should have a Fredholm determinant.

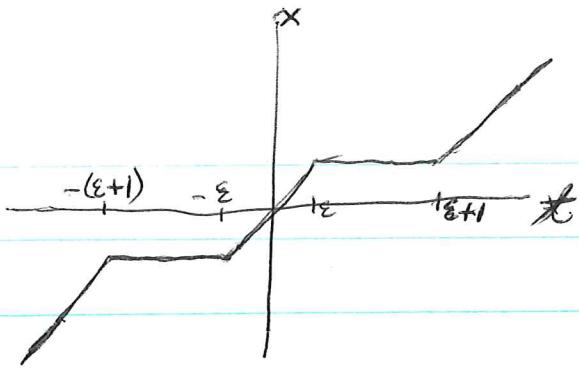
For example

$$\begin{aligned} \text{trace} &= \int_0^\infty e^{2ikx(t)} g(-t) dt \\ &= \int_{-\epsilon}^{\epsilon+1} e^{2ike} (-\bar{c}) dt = -\bar{c} e^{2ike} \end{aligned}$$

so it is clear more or less that a determinant exists for the integral equation at the bottom of the preceding page

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$$x(t) = \begin{cases} t & 0 \leq t \leq \varepsilon \\ \varepsilon & \varepsilon \leq t \leq \varepsilon + 1 \\ t-1 & \varepsilon + 1 \leq t < \infty \end{cases}$$



$$\frac{dx}{dt} = 1 - \pi(t)$$

$$\pi(t) = \begin{cases} 1 & t \in [\varepsilon, \varepsilon + 1] \\ 0 & \text{otherwise} \end{cases}$$

$$\frac{d}{dt} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} ik \frac{dx}{dt} & C\pi(t) \\ \bar{C}\pi(t) & -ik \frac{dx}{dt} \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

or

$$\left(\frac{d}{dt} - ik \frac{dx}{dt} \right) \psi = \boxed{\quad} V\psi$$

where

$$(V\psi)(t) = g(t)\psi(-t)$$

$$g(t) = \begin{cases} C\pi(t) & t \geq 0 \\ -\bar{C}\pi(t) & t \leq 0 \end{cases}$$

So this leads to the integral equation

$$\psi(t) = \text{const. } e^{ikx} + \int_{-\infty}^t e^{ik(x-x')} g(t') \psi(-t') dt'$$

which still has the form

$$\psi = \varphi + G_k^+ V \psi$$

except that G_k^+ is the Green's function for

$$\left(\frac{d}{dt} - ik \frac{dx}{dt} \right)$$

Can we interpret $\det(I - G_k^+ V)$ as a char. poly.

This time we ~~will not~~ work with functions of t .

Restrict to functions on $[a, \infty)$ where $a < -\varepsilon - 1$.

Then $\frac{d}{dt}$ ~~is a bounded linear operator~~ with boundary condition $u(a) = 0$ gives an operator A_0 with inverse

$$A_0^{-1} = \int_a^x f(x') dx'$$

If $\alpha(t) = \frac{dx}{dt}$, then

$$A_0^{-1}(A_0 - ik\alpha) = I - ik A_0^{-1}\alpha$$

where $((A_0^{-1}\alpha)f)(t) = \int_a^t \alpha(t') f(t') dx'$ is a Volterra

operator. Thus $A_0^{-1}(A_0 - ik\alpha)$ has determinant 1. Thus it seems that

$$\begin{aligned} I - G_k^+ V &= (A_0 - ik\alpha)^{-1}(A - ik\alpha) & A = A_0 - V \\ &= \boxed{} (I - ik A_0^{-1}\alpha)^{-1} A_0^{-1}(A - ik\alpha) \end{aligned}$$

so that

$$\begin{aligned} \det(I - G_k^+ V) &= \det(A_0^{-1}(A - ik\alpha)) \\ &= \det(A_0^{-1}A) \det(I - ik A_0^{-1}\alpha) \end{aligned}$$

~~Now~~ assuming $A_0^{-1}A$ is invertible. If this formal argument is correct, it ^{ought to} follow that $e^{ikA} - h$ is of the form ~~of a characteristic polynomial~~ of a characteristic polynomial.

Check more carefully:

Start with

$$\frac{d}{dx} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} ik & p \\ \bar{p} & -ik \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

on $0 \leq x < \infty$
with $u_1(0) = u_2(0)$

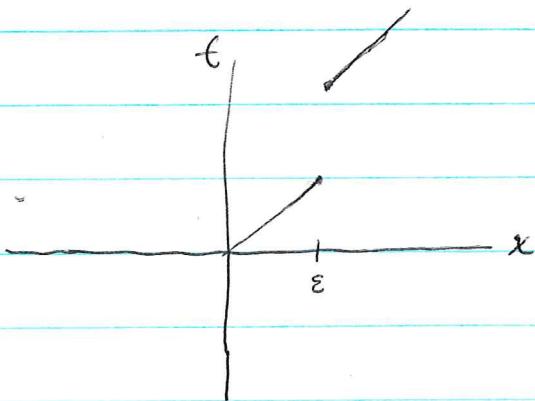
and  where $p = c\delta(x-\varepsilon)$, ε fixed >0. We write this

$$d \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} ik dx & pdx \\ \bar{p} dx & -ik dx \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

where $p dx = c \delta(x-\varepsilon) dx$. We interpret this by choosing a measure dt such that dx and $\delta(x-\varepsilon) dx$ are abs. continuous wrt it, e.g.

$$dt = dx + \delta(x-\varepsilon) dx$$

$$t = \begin{cases} x & 0 \leq x < \varepsilon \\ x+1 & \varepsilon < x \end{cases}$$



Then we put

$$\frac{dx}{dt} = \alpha(t), \quad \frac{\delta(x-\varepsilon) dx}{dt} = \boxed{\text{shaded box}} \beta(t)$$

and we get

$$\frac{d}{dt} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} ik\alpha & c\beta \\ -c\bar{\beta} & -ik\alpha \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$$

Now we put this onto $-\infty < t < \infty$ in the usual way

$$\frac{du}{dt} = ik\alpha u + \boxed{V u}$$

where

$$(Vu)(t) = g(t)u(-t)$$

and

$$g(t) = \begin{cases} c\beta(t) & t > 0 \\ -\bar{c}\beta(-t) & t \leq 0 \end{cases}$$

Solve the DE: using $\frac{dx}{dt} = \alpha$:

$$e^{-ikx} \left(\frac{du}{dt} - ik \frac{dx}{dt} u \right) = e^{-ikx} V_u$$

$$u = \text{const. } e^{ikx} + \int_{-\infty}^t e^{ik(x-x')} (V_u)(t') dt'$$

$\underbrace{(V_u)(t')}$
 $\overbrace{g(t) u(-t')}$

where

$$G_k^+(t, t') = \begin{cases} e^{ik(x-x')} & t > t' \\ 0 & t < t' \end{cases}$$

is the Green's function for $\frac{d}{dt} - ik\alpha$.

Now my goal is to compute $\det(I - G_k^+ V)$.

Since $g(t)$ is supported to the right of $a = -\varepsilon - 1$, this determinant can be computed on the interval $[a, \infty)$.

Let $A_0 = \frac{d}{dt}$ on $L^2(a, \infty)$ with boundary condition $f(a) = 0$. Then A_0^{-1} is a bounded operator

$$(A_0^{-1} f)(t) = \int_a^t f(t') dt'$$

and $G_k^+(t, t')$ is the kernel for the operator $(A_0 - ik\alpha)^{-1}$.

$$\begin{aligned} ((A_0 - ik\alpha)^{-1} f)(t) &= \boxed{\left[(e^{ik\alpha} A_0 e^{-ik\alpha})^{-1} f \right](t)} \\ &= \left[(e^{ik\alpha} A_0^{-1} e^{-ik\alpha}) f \right](t) \\ &= e^{ikx} \int_a^t e^{-ikx(t')} f(t') dt' \end{aligned}$$

Thus on $L^2((a, \infty))$, $I - G_k^+ V = I - (A_0 - ik\alpha)^{-1} V$ ~~the rest~~.

January 20, 1979

Review: I started with a Dirac system

$$\frac{d}{dx} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} ik & p \\ \bar{p} & -ik \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \quad 0 \leq x < \infty$$

$$u_1(0) = u_2(0)$$

where $p = c\delta(x-\varepsilon)$, $\varepsilon > 0$. Introduce new independent variable t in order to make sense of this DE:

$$dt = dx + \delta(x-\varepsilon)dx$$

and then the system becomes $\frac{d}{dt} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} ikx & c\beta \\ \bar{c}\beta & -ikx \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$
on $0 \leq t < \infty$, same bdy condition
at $t=0$, where $\alpha = \frac{dx}{dt}$, $\beta = 1 - \alpha$. Then I piece $u_1(t), u_2(-t)$ together to get $u(t)$ defined on \mathbb{R} satisfying

$$(*) \quad \frac{du}{dt} = ik\alpha u + Vu$$

where

$$(Vu)(t) = g(t)u(-t) \quad g(t) = \begin{cases} c\beta(t) & t > 0 \\ -g(t-t) & t \leq 0 \end{cases}$$

The Green's function for $\frac{d}{dt} - ik\alpha$ on $L^2(-\infty < t < \infty)$ is

$$G_k^+(t, t') = \begin{cases} e^{ik(x(t)-x(t'))} & t > t' \\ 0 & t < t' \end{cases}$$

for $\text{Im } k > 0$. Consequently $(*)$ is equivalent to

$$u = \varphi + G_k^+ V u$$

where $\varphi(t) = \text{const. } e^{ikx(t)}$.

The problem is now to compute and understand $\det(I - G_k^+ V)$. Since

$$(G_k^+ V f)(t) = \int_{-\infty}^t e^{ik(x(t)-x(t'))} g(t') f(-t') dt'$$

$$= \int_t^\infty e^{ik(x(t) + x(t'))} \underbrace{g(-t') f(t')}_{\text{supported in } |t'| \leq \text{const.}} dt'$$

it would seem that the determinant is well-defined by the Fredholm formulas.

To compute it, or rather, to interpret this det as a char. poly., let's restrict to functions defined on $[a, \infty)$ where $a < 0$, and let A_0 be the operator on $L^2(a, \infty)$ given by $\frac{d}{dt}$ with the bdry condition $f(a) = 0$. Then

$$(A_0^{-1}f)(t) = \int_a^t f(t') dt'$$

and

$$((A_0 - ik\alpha)^{-1}f)(t) = \int_a^t e^{ik(x(t) - x(t'))} f(t') dt'$$

$$\therefore (A_0 - ik\alpha)^{-1} = e^{ikx} A_0^{-1} e^{-ikx}$$

Then on $L^2(a, \infty)$

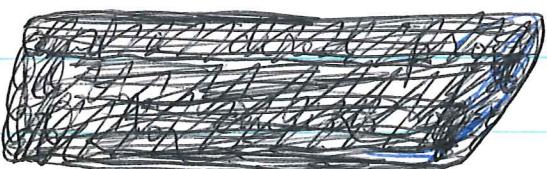
$$I - G_k^+ V = I - (A_0 - ik\alpha)^{-1} V$$

and

$$(I - A_0^{-1} ik\alpha)(I - G_k^+ V) = I - A_0^{-1} ik\alpha - \underbrace{(I - A_0^{-1} ik\alpha)(A_0 - ik\alpha)^{-1} V}_{A_0^{-1}}$$

The proof of the assertion ~~formally~~ is

$$(I - A_0^{-1} ik\alpha)(A_0 - ik\alpha)^{-1} = A_0^{-1}(A_0 - ik\alpha)(A_0 - ik\alpha)^{-1} = A_0^{-1}$$



where one uses that ~~the domain~~
 $A_0^{-1}(A_0 - ik\alpha) = I - A_0^{-1} ik\alpha$ on D_{A_0} .

Next note that

$$(A_0^{-1} \alpha f)(t) = \int_a^t \alpha(t') f(t') dt'$$

is a Volterra kernel, hence $\det(1 - A_0^{-1} ik\alpha) = 1$.

Thus

$$\det(1 - G_k^+ V) = \det(1 - A_0^{-1} ik\alpha - A_0^{-1} V)$$

which has the ^{gen.} characteristic polynomial form, since k appears linearly inside.

There might be some problem ultimately with $\det(1 - A_0^{-1} ik\alpha) = 1$, since the operator $A_0^{-1} \alpha$ and even A_0^{-1} might not be of trace class. It is not obvious ~~■~~ how to define

$$\det(1 - A_0^{-1} ik\alpha)$$

so maybe it is necessary to work on a finite interval, in which case things should be OK.

Let's compute to the first order

$$\begin{aligned} (G_k^+ V f)(t) &= \int_a^t e^{ik(x(t) - x(t'))} g(t') f(-t') dt' \\ &= \int_{-t}^{-a} e^{ik(x(t) + x(t'))} g(-t') f(t') dt' \quad t' \geq -t \end{aligned}$$

$$-a = \varepsilon + 1.$$

$$K(t, t') = \Theta(t+t') e^{ik(x(t) + x(t'))} g(-t')$$

$$\text{tr } K = \int_a^{-a} K(t, t) dt = \int_a^{-a} \Theta(2t) e^{ik2x(t)} (-\bar{g}(t)) dt$$

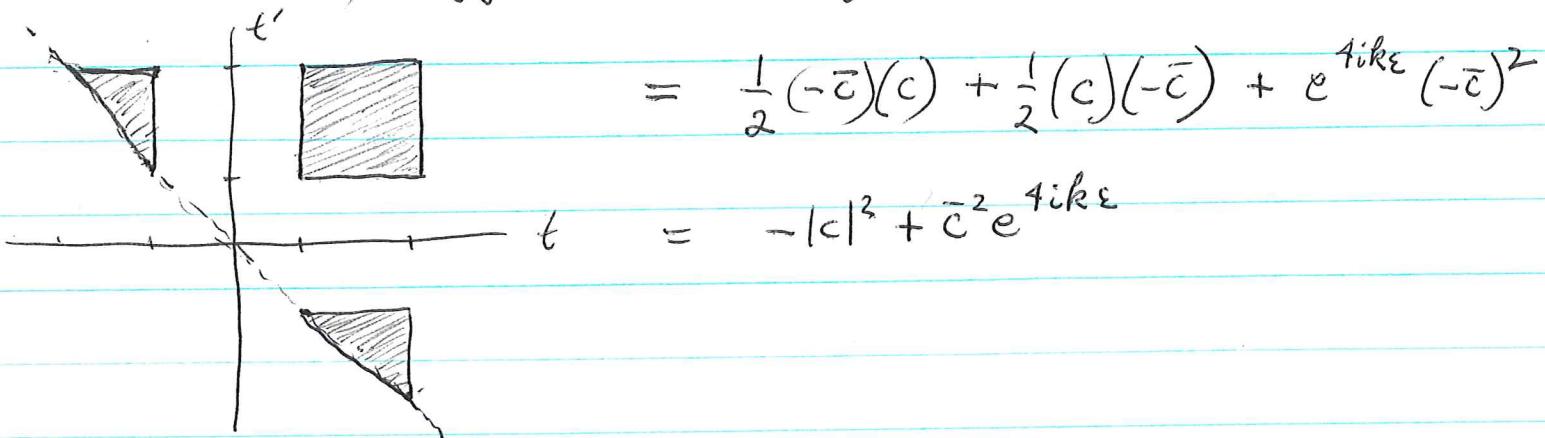
$$= \int_{-\infty}^{\varepsilon+1} e^{2ik\varepsilon} (-\bar{c}) dt = -\bar{c} e^{2ik\varepsilon}$$

2nd order term: $\text{tr}(A^2 K) = \iint_{t>t'} \begin{vmatrix} K(t,t) & K(t,t') \\ K(t',t) & K(t',t') \end{vmatrix} dt dt'$

$$= \frac{1}{2} (\text{tr } K)^2 - \text{tr } (K^2)$$

Now

$$\text{tr}(K^2) = \iint \Theta(t+t') e^{ik(x+x')} g(-t') \Theta(t'+t) e^{-ik(x'+x)} g(-t) dt dt'$$



Thus

$$\det(1 - G_k^+ V) = 1 + \bar{c} e^{2ik\varepsilon} + \frac{1}{2} (\bar{c} e^{2ik\varepsilon})^2 - \frac{1}{2} (-|c|^2 + \bar{c}^2 e^{4ik\varepsilon}) +$$

$$= 1 + \bar{c} e^{2ik\varepsilon} + \frac{1}{2} |c|^2 + O(c^3)$$

The question to answer: Do you have an analogue of the Wronskian formula for $\det(1 - G_k^+ V)$ in the Dirac setup?

Solve the Dirac system with $(u_1, u_2)(0) = (1, 1)$ and take the Wronskian with the good solution $(e^{ikx}, 0)$ behavior for $x \gg 0$. Do this both for the free & perturbed systems and compare.

We have already solved the Dirac system and found
(p. 478)

$$\begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} e^{ikx} \\ e^{-ikx} \end{pmatrix} \quad \text{for } 0 < x < \varepsilon$$

$$= \begin{pmatrix} B(k) e^{ikx} \\ A(k) e^{-ikx} \end{pmatrix} \quad \text{for } \varepsilon < x$$

where

$$B(k) = \frac{1}{\sqrt{1-h^2}} (1 - h e^{-2ik\varepsilon})$$

$$A(k) = \frac{1}{\sqrt{1-h^2}} (1 - \bar{h} e^{2ik\varepsilon})$$

and

$$\frac{1}{\sqrt{1-h^2}} \begin{pmatrix} 1 & -h \\ -\bar{h} & 1 \end{pmatrix} = \exp \left(\begin{pmatrix} 0 & c \\ \bar{c} & 0 \end{pmatrix} \right)$$

so the two Wronskians are:

$$\begin{vmatrix} B(k) e^{ikx} & e^{ikx} \\ A(k) e^{-ikx} & 0 \end{vmatrix} = -A(k), \quad \begin{vmatrix} e^{ikx} & e^{-ikx} \\ e^{-ikx} & 0 \end{vmatrix} = -1$$

and so therefore we conjecture

$$\det(I - Q_k^\dagger V) = A(k) = \frac{1}{\sqrt{1-h^2}} (1 - \bar{h} e^{2ik\varepsilon}).$$

Now

$$\exp \left(\begin{pmatrix} 0 & c \\ \bar{c} & 0 \end{pmatrix} \right) = \exp \left\{ \left(\begin{pmatrix} e^{i\theta} & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & |c| \\ |c| & 0 \end{pmatrix} \begin{pmatrix} e^{-i\theta} & 0 \\ 0 & 1 \end{pmatrix} \right) \right\}$$

$$= \begin{pmatrix} e^{i\theta} & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \cosh |c| & \sinh |c| \\ \sinh |c| & \cosh |c| \end{pmatrix} \begin{pmatrix} e^{-i\theta} & 0 \\ 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} \cosh |c| & e^{i\theta} \sinh |c| \\ e^{-i\theta} \sinh |c| & \cosh |c| \end{pmatrix}$$

$$c = |c| e^{i\theta}$$

$$= \begin{pmatrix} 1 + \frac{1}{2}|c|^2 & c \\ \bar{c} & 1 + \frac{1}{2}|c|^2 \end{pmatrix} + O(c^3)$$

$$\therefore -h = e^{i\Theta} \tanh |c| = c + O(c^3)$$

$$\begin{aligned} \therefore A(k) &= \cosh |c| + e^{-i\Theta} \sinh |c| e^{2ik\varepsilon} \\ &= \left(1 + \frac{|c|^2}{2} + \bar{c} e^{2ik\varepsilon} + O(c^3) \right) \end{aligned}$$

which checks.

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Yesterday we found for

$$\left(\frac{d}{dx} - ik\right) u = Vu \quad \text{on } \mathbb{R}$$

$$\text{where } (Vu)(x) = p(x)u(-x)$$

$$p(-x) = -\overline{p(x)}$$
$$p=0 \quad \text{for } |x| \gg 0$$

the conjectural formula

$$\det(1 - G_k^+ V) = A(k)$$

where $\boxed{\text{solution}}$ $u(x) = A(k) e^{ikx} \quad x \ll 0$ and u is the $\boxed{\text{solution}}$ solution with $u(0) = 1$. The

motivation for the formula comes by applying our prescription for the Schröd. DE to the Dirac DE

$$\frac{d}{dx} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} ik & p \\ \bar{p} & -ik \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \quad \text{on } 0 \leq x < \infty$$

$$u_1(0) = u_2(0)$$

Thus we ~~compute~~ the Wronskian of $\boxed{\begin{pmatrix} u_1 \\ u_2 \end{pmatrix}}$ ^{normalized with $u_1(0)=u_2(0)=1$} with the $\boxed{\text{solution}}$ good $\boxed{\text{for }} x \gg 0$, and divide it by the corresponding Wronskian with $p=0$:

$$\frac{\begin{vmatrix} B(k) e^{ikx} & e^{ikx} \\ A(k) \bar{e}^{ikx} & 0 \end{vmatrix}}{\begin{vmatrix} e^{ikx} & e^{ikx} \\ e^{-ikx} & 0 \end{vmatrix}} = A(k)$$

Now the problem is to understand what is going on here.