

c) $u_i w \otimes v_i = x_i \otimes y_i$ central

suppose $\rho \Rightarrow \begin{cases} u_i w \rho(v_i) = 1 \\ \rho(u_i w) v_i = 1. \end{cases} \Rightarrow u_i \rho(v_i) = w^{-1}$

$\text{tr}(u_i v_j) = \delta_{ij}$

$\rho(a) = \text{tr}(w^{-1} a)$

Final assertion. Let τ be canonical trace.

Then any ρ have form $\rho(a) = \tau(w a)$ some $w \in A$.

Take $u_i z \otimes v_i = u_i \otimes z v_i$ for $x_i \otimes y_i$

$\rho(u_i z) v_i = \rho(u_i) z v_i = 1$

$u_i z \rho(v_i) = u_i \rho(z v_i) = 1$

$u_i z \tau(w v_i) = \underbrace{u_i \tau(w z v_i)} = 1$

$\tau(v_j) z = \tau(w z v_i) = \tau(v_j)$

"
 $\int \delta_{ij}$

$w z = 1.$

$w = z^{-1}$

- A) Define the p evaluations.
 B) prove that the evaluations are faithful (i.e. if α is "captured" by a row evaluation it is also captured by a column evaluation).
 C) (perhaps) we have to prove we can keep the system symmetrical after the changes. Perhaps this is a purely cosmetic requirement.
 (5) Consider "restricted" conditions which are almost constant i.e. j is mapped $j' \in \{j, j+1, \dots, j+p\}$. It is possible to arrange "critical" branches (i.e. branches which form a restricted condition) such that nodes with root in D appears before root in R . Further more we can ensure that along a branch the first k_1 places are rooted in D while the last $k - k_1$ are rooted in R . This ensures we can define a weight-function which behaves properly.

d) Conclusion is that if $\omega \in A^*$, then
 can take $x_i \otimes y_i = u_i \omega \otimes v_i$
 and $\rho(a) = \tau(\omega^* a)$.

March 10. Go over Joachim's remarks about P.

$$T(a) \rightarrow R\tilde{a} = \Omega^{\omega}(\tilde{a})$$

Two possibilities ~~$a_0 da_1$~~

$$(a_0, \dots, a_{2n}) \mapsto a_0 da_1 \dots da_{2n}$$

$$(a_1, \dots, a_{2n}) \mapsto da_1 \dots da_{2n}$$

defines $e_{2n} : T(a) \rightarrow \Omega^{2n} \tilde{a}$

Then ~~what~~ P is supposed to be $e_{2n} P_{\lambda} e_{2n}$

Other possibility is to map

$$a_0, \dots, a_{2n} \mapsto a_0 \circ \dots \circ a_{2n}$$

So what was he saying?

$$X(R\tilde{a}) = \Omega(a)$$

$$\parallel$$

$$X(T(a))$$

$$\mathbb{C} \subset \mathbb{C} \subset \rho(A) \subset \rho(A)^2 \subset \rho(A)^3 \subset$$

RA

IA

~~IA~~

IA²

$$\begin{aligned} a_0 \circ a_1 \circ a_2 &= a_0 \circ (a_1 a_2 - da_1 da_2) \\ &= a_0 a_1 a_2 - a_0 da_1 da_2 - da_0 da_1 a_2 - da_0 a_1 da_2 \\ a_1 \circ a_2 &= a_1 a_2 - da_1 da_2 \end{aligned}$$

e

$$e_2(a_0, a_1, a_2) = -a_0 da_1 da_2 - da_0 a_1 da_2 - da_0 da_1 a_2$$

$$e_2(a_1, a_2) = -da_1 da_2.$$

$$a_0 \circ a_1 \circ a_2 \circ a_3 = (a_0 a_1 - da_0 da_1) \circ (a_2 a_3 - da_2 da_3)$$

$$= a_0 a_1 a_2 a_3 - d(a_0 a_1) d(a_2 a_3)$$

$$- a_0 a_1 da_2 da_3 - da_0 da_1 a_2 a_3 + da_0 da_1 da_2 da_3$$

~~OK~~

$$b'(a_0 da_1 \dots da_n) = (-1)^{n-1} a_0 da_1 \dots da_{n-1} a_n$$

$$= \sum_{i=1}^{n-1} (-1)^{i-1} a_0 \dots d(a_i a_{i+1}) \dots$$

$$+ a_0 a_1 da_2 \dots da_n$$

$$\iff b'(a_0, \dots, a_n)$$

If $a_0 = 1$, get $\sum_{i=1}^n (-1)^i da_1 \dots d(a_i a_{i+1}) \dots da_n + a_1 da_2 \dots da_n$

Then $\left[\begin{pmatrix} b' & 1 \\ & -b' \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right] = \begin{pmatrix} 1 & 0 \\ -b'+b' & 1 \end{pmatrix}$

So lifting is $P \begin{pmatrix} b' & 1 \\ -b' & -b' \end{pmatrix} \begin{pmatrix} 0 \\ P_\lambda \end{pmatrix}$

$$= \begin{pmatrix} P_\lambda & 0 \\ b'G_\lambda - G_\lambda b' & P_\lambda \end{pmatrix} \begin{pmatrix} P_\lambda \\ -b'P_\lambda \end{pmatrix} = \begin{pmatrix} P_\lambda \\ -G_\lambda b' P_\lambda - P_\lambda b' P_\lambda \end{pmatrix}$$

$$0 \longrightarrow P_\lambda C^{\bullet} [1] \xrightarrow{\begin{pmatrix} 0 \\ 1 \end{pmatrix}} P \cdot \tilde{\Omega} \tilde{A} \xrightarrow{\begin{pmatrix} N_\lambda & 0 \end{pmatrix}} P_\lambda C^{\bullet} \longrightarrow 0$$

$-b'$ b'

I've been sloppy about the N , but it makes

$$b' \begin{pmatrix} P_\lambda & b' P_\lambda \end{pmatrix} = b'^2 P_\lambda = 0 \quad \begin{pmatrix} P_\lambda & b' P_\lambda \end{pmatrix} b' \begin{pmatrix} P_\lambda \end{pmatrix}$$

k Cuntz excision in periodic cyclic homology
 Review what we know already.

~~Excision~~

~~Excision~~

~~Excision~~

$$\begin{array}{ccccccc}
 & & & & J & & \\
 & & & & \downarrow & & \\
 0 & \longrightarrow & I & \longrightarrow & TA & \longrightarrow & A \longrightarrow 0 \\
 & & \downarrow & & & & \downarrow \\
 0 & \longrightarrow & K & \longrightarrow & TA & \longrightarrow & B \longrightarrow 0 \\
 & & \downarrow & & & & \\
 & & J & & & &
 \end{array}$$

$I^\infty = \{I^k\}$

Before ~~excision~~ be established that excision in cyclic cohomology holds for ~~excision~~

$$J^\infty \longrightarrow R \longrightarrow R/J^\infty \quad \text{non-unital}$$

provided we can find suitable left J -linear lifting of mult. $J^n \longrightarrow J \otimes J$

$$\begin{array}{ccc}
 & & J \otimes J \\
 & \nearrow \text{J-module map } \psi & \downarrow \\
 J^2 & \longrightarrow & J^2
 \end{array}$$

Then $J^{n+2} \longrightarrow J^{n+1} \otimes J$ for all n .

Better $J^n \longrightarrow J^{n-1} \otimes J \longrightarrow (J^{n-2} \otimes J) \otimes J$

t | excision in per eye coh.

$$0 \rightarrow J \rightarrow A \rightarrow B \rightarrow 0$$

$$\leftarrow \text{HP}(A, J) \leftarrow \text{HP}(A) \leftarrow \text{HP}(B)$$

$$\downarrow$$

$$\text{HP}(J)$$

to prove that ~~assertion~~ map $\text{HP}(A, J) \rightarrow \text{HP}(J)$ is isom.

Assume that $\text{HP}(TA, IA) \xrightarrow{\sim} \text{HP}(IA)$ for all A .

Then this should be enough.

Shift to covariant functors. F

Given $0 \rightarrow J \rightarrow A \rightarrow B \rightarrow 0$ get

~~XXXXX~~

$$\rightarrow F(A, J) \rightarrow F(A) \rightarrow F(B) \rightarrow$$

$$\uparrow$$

$$F(J)$$

Suppose we know $F(IA) \xrightarrow{\sim} F(TA, IA)$
for all A .

$$\begin{array}{ccccccc}
 & & 0 & & & & \\
 & & \uparrow & & & & \\
 0 & \rightarrow & J & \rightarrow & A & \rightarrow & B \rightarrow 0 \\
 & & \uparrow & & \uparrow & & \text{"} \\
 0 & \rightarrow & K & \rightarrow & TA & \rightarrow & B \rightarrow 0 \\
 & & \uparrow & & \uparrow & & \\
 & & IA & \xrightarrow{\sim} & IA & &
 \end{array}$$

So apparently we define on $Q\tilde{A}$ a derivation.

Should we do stable multipliers, i.e. multipliers for $M_n Q$? Read Wodzicki about Kasnerstein lemma